# User's Manual <br> Model DRC-84C Digital Cryogenic Thermometer/Controller 

## Obsolete Notice:

This manual describes an obsolete Lake Shore product. This manual is a copy from our archives and may not exactly match your instrument. Lake Shore assumes no responsibility for this manual matching your exact hardware revision or operational procedures. Lake Shore is not responsible for any repairs made to the instrument based on information from this manual.


Fax: (614) 891-1392
Telephone: (614) 891-2243


#### Abstract

Methods and apparatus disclosed and described herein have been developed solely on company funds of Lake Shore Cryotronics, Inc. No government or other contractual support or relationship whatsoever has existed which in any way affects or mitigates proprietary rights of Lake Shore Cryotronics, Inc. in these developments. Methods and apparatus disclosed herein may be subject to U.S. Patents existing or applied for. Lake Shore Cryotronics, Inc. reserves the right to add, improve, modify, or withdraw functions, design modifications, or products at any time without notice. Lake Shore shall not be liable for errors contained herein or for incidental or consequential damages in connection with furnishing, performance, or use of this material.


Table of Contents
Section Page
I. General Information
1.1 Introduction ..... I
1.2 Description ..... 1
1.3 Major Assemblies Supplied ..... 3
1.4 Ordering of Replacement or Additional Sensors ..... 3
II. Installation
2.1 Introduction ..... 5
2.2 Initial Inspection ..... 5
2.3 Power Requirements ..... 5
2.4 Grounding Requirements ..... 5
2.5 Installation ..... 5
2.6 Repackaging for Shipment ..... 6
III. Operating Instructions
3.1 Introduction ..... 9
3.2 Controls, Indicators, Connectors ..... 9
3.3 Temperature Readout ..... 12
3.4 Analog Control ..... 12
3.5 Analog Output of Temperature ..... 13
3.6 Standard DT-500-DRC and DT-500CU-DRC-36 Curves ..... 13
3.7 The 10-Sensor Selector Switch ..... 13
3.8 Remote Parallel BCD Input/Output Option ..... 14
3.9 IEEE Interface Option ..... 26
3.9.1 General IEEE Specifications and Operation ..... 26
3.9.2 Specific Operation of the DRC8-IEEE Interface ..... 27
3.9.3 Sample Programming ..... 32
3.10 Installation of DRC BCD/L-A Option Board ..... 34
3.11 Installation of DRC IEEE Option Board ..... 35
3.12 Rack Mounting the DRC-84C ..... 36
3.13 Error Conditions ..... 36
IV. Theory of Operation
4.1 Introduction ..... 37
4.2 General Description ..... 37
4.3 Detailed Description ..... 39
4.3.1 Power Supplies ..... 39
4.3.2 Precision Current Sources and Input Switching ..... 40
4.3.3 A/D Converter and Microprocessor Hardware ..... 40
4.3.4 Software ..... 41
4.3.5 Analog Control and Set Point ..... 44
4.3.6 Digital Display Board ..... 45

> Table of Contents (cont'd.)

Section Page
v. Calibration and Troubleshooting5.1 Introduction47
5.2 Test Equipment ..... 47
5.3 General Remarks ..... 47
5.4 Instrument Calibration ..... 47
5.4.1 Current Sources ..... 47
5.4.2 A/D Converter ..... 48
5.4.3 D/A Converter ..... 48
5.4.4 Output Buffer ..... 51
5.4.5 DRC L/A Option (if present) ..... 51
5.5 Instrument Tests ..... 55
VI. Replaceable Parts List
6.1 Main Board Components ..... 55
6.2 DRC-84C BCD-L/A and IEEE Components List ..... 63

## Table of Illustrations

| Reference | Description | Page |
| :---: | :---: | :---: |
| Figure 1.1 | Model DRC-84C Digital Cryogenic Thermometer/Controller |  |
| Figure 2.1 | Sensor, Cable, and Monitor Connections | 7 |
| Table 3.1 | Entry Number Correlation | 9 |
| Figure 3.1 | DRC-84C Front Panel | 11 |
| Figure 3.2 | DRC-84C Back Panel | 11 |
| Table 3.2 | Relative Gain for BCD Option | 15 |
| Table 3.3 | Reset Time Constants for BCD Option | 16 |
| Figure 3.3 | DRC-84C-IEEE Panel Layout | 28 |
| Table 3.4 | DT-500-DRC Voltage-Temperature Characteristic | 17 |
| Figure 3.4 | Model DRC-84C showing Rack Mount Kit | 35 |
| Table 3.5 | SW-10A Connector Detail | 20 |
| Table 3.6 | BCD Temperature Output - Mode1 DRC-Series Remote I/O | 21 |
| Table 3.7 | DIN Standard Curve for Platinum Sensors | 22 |
| Figure 4.1 | DRC-84C Block Diagram | 38 |
| Figure 4.2 | Software F1ow Diagram | 43 |
| Table 5.1 | Decimal-hex Table | 49 |
| Table 5.2 | Data for Standard Curves (D \& E) | 49 |
| Table 5.3 | DRC-84C Troubleshooting Notes | 52 |
| Table 5.4 | DRC-84C Troubleshooting Notes | 53 |
| Figure 6.1 | DRC-84C Power Supply | 67 |
| Figure 6.2 | DRC-84C Current Source, Input Connections, Switching | 69 |
| Figure 6.3 | DRC-84C Microprocessor Section | 71 |
| Figure 6.4 | DRC-84C Analog Output Section | 73 |
| Figure 6.5 | DRC-84C Component Layout | 75 |
| Figure 6.6 | DRC-84C Display Board | 77 |
| Figure 6.7 | DRC-84C Display Board Component Layout | 77 |
| Figure 6.8 | DRC-84C BCD/L-A Option | 79 |
| Figure 6.9 | DRC-84C BCD/L-A Option Component Layout | 79 |
| Figure 6.10 | DRC-84C IEEE Option | 81 |
| Figure 6.11 | DRC-84C IEEE Option Component Layout | 81 |

## Specifications, DRC-84C Temperature Controller

## Input:

Temperature Range: 1.4 to 330 K with standard silicon diode DRC Sensor (to 380 K with other silicon Sensors) 30 to 800 K with platinum sensor. Silicon diodes cannot be exposed to temperatures above their useful range. Sensors (order separately): Silicon Diode: DT-500-DRC DT-500CU-DRC-36 or any calibrated DT-500 Series Diode (with DRC-Precision Option). See below for proper response curve. Platinum RTD: PT-101, PT-102 PT-103, or any other 100 -ohm, $0.00385 /{ }^{\circ} \mathrm{C}$ sensor See response curve details below.
Sensor Input: Two section input (silicon-diode and platinum RTD). Front-panel switch selects either section Each section accommodates two sensors with 4-terminal input for each sensor. Front-panel switches enable independent selection of either sensor within each section as display and/or control sensor. Display/control sensors cannot be mixed between silicon and platinum sections.
Sensor Excitation: Current source. 10. microamperes for each sensor in silicon-diode section, 0.5 milliampere $( \pm 0.005 \%$ ) for each sensor in platinum RTD section.
Sensor Response Curves: Silicon Diode Section: Domestic US units require Sensor Curve "D". Export units require Sensor Curve " E ". Sensor curves subject to change, refer to manual for proper curve when reordering Sensors. Curves to match existing Sensors available on special request. See also DRC-Precision Option. Platinum RTD Section: Standard response curve is based on $0.1 \%$ interchangeability at $0^{\circ} \mathrm{C}$ and temperature coefficient $\left(0-100^{\circ} \mathrm{C}\right)$ of $0.00385 /{ }^{\circ} \mathrm{C}$. Refer to Lake Shore PT-100 Technical Data for details. Special calibrations are available and may be incorporated into the 84C via the DRC-Precision Option.
Input Resistance: Greater than 1000 megohms. Maximum Sensor Power Dissipation: Silicon-diode: $25 \mu \mathrm{~W}$ at 4.2 K . Platinum: $25 \mu \mathrm{~W}$ below 80 K increasing to $100 \mu \mathrm{~W}$ at 273 K .

## Temperalure Readout:

Display: 4 digit, 1.1 cm ( $0.43^{\prime \prime}$ ) LED shows temperature directly in Kelvin or Celsius as selected by front-panel switch. Display Sensor can be selected independent of Control Sensor within each section.
Resolution: 0.1 K or $0.1^{\circ} \mathrm{C}$. "Scale Expand" increases resolution to 0.01 K for temperatures below 30 K and 0.05 K for $30-100 \mathrm{~K}$ (no increase in accuracy).

Accuracy ( $\mathbf{2 0 - 2 5}{ }^{\circ} \mathbf{C}$ ambient): Silicon-diode: $\pm 0.5 \mathrm{~K}$ at 4 K and $77 \mathrm{~K}, \pm 1.0 \mathrm{~K}$ at 300 K with standard sensor. Accuracy with Lake Shore calibrated Sensor and DRCPrecision $\pm 0.1 \mathrm{~K}$ or better depending on calibration range. Platinum RTD: Conforms to DIN 43760 tolerances $\pm 0.1 \mathrm{~K}$. See Lake Shore PT-100 Technical Data for details. Calibrated Sensor and DRC-Precision improves accuracy to $\pm 0.01 \mathrm{~K}$ depending on range.

## Temperalure Control:

Set-Point: Digital thumbwheel selection directly in Kelvin, (+) Celsius, or (-) Celsius as determined by frontpanel switch. Remotely settable in Kelvin with BCD or IEEE-488 Option.
Set-Point Resolution: 0.1 K or $0.1^{\circ} \mathrm{C}$.
Typical Controllability: 0.1 K or better in a properly designed system.
Control Mode: Proportional (gain) and integral (reset). Set via front panel or remotely with BCD or IEEE-488 option.
Heater Output: $\mathrm{HI}: 0-25$ watts ( 1 A max, 25 V max) LO: 0-10 watts nominal ( 1 A max or 12 V max). Isolated output. 25 -ohm heater is recommended.
Control Sensor: Selected by front-panel pushbutton independent of Display Sensor within either section.

## General:

Monltor Output: Buffered output of 1X Display Sensor voltage (silicon) and $5 \times$ Display Sensor voltage (platinum). Additional outputs listed below as options
Dimensions, Weight: 432 mm wide $\times 102 \mathrm{~mm}$ high $\times$ 330 mm deep (17 in $\times 4$ in $\times 13 \mathrm{in}$ ). Style L, full-rack package. Net weight 8.4 kg ( 18.5 lbs ).
Power: $90-110,105-125$, or $210-250 \mathrm{VAC}, 50$ or 60 Hz , 75 watts.
Accessories Supplied: Mating connectors for sensor inputs and monitors, instruction manual.

## Optlons and Accessories Available:

Model DRC8-BCD. Parallel BCD interface, TTL compatible. Allows remote control of set-point, gain, reset, and provides BCD output of temperature in Kelvin and Sensor selected (either from front-panel or optional SW-10A)
Model DRC8-IEEE. 488 interface. Allows remote control of set-point, gain, reset and provides digital output of temperature in Kelvin and Sensor selected (either from front-panel or optional SW-10A).
Model DRC8-L/A. Analog output proportional to Kelvin temperature for use with recorders, or other readouts. $10 \mathrm{mV} / \mathrm{K}$ at $<10$ ohm output resistance.
Model KT-LA. Analog output identical to DRC8-L/A except for use when unit is also equipped with DRC8BCD
Model KT-BCD. Parallel BCD interface identical to DRC8-BCD except for use when unit is also equipped with DRC8-L/A.
Model SW-10A. 10-Sensor Selector Switch for use with DRC Thermometer or Controller. Pushbutton selection of any one of up to 10 sensors. Connects to Sensor "B" position. Sensor selected is also identified via digital interfaces. Dimensions: 216 mm wide $\times 102 \mathrm{~mm}$ high $\times 330 \mathrm{~mm}$ deep ( $81 / 2$ in $\times 4$ in $\times 13 \mathrm{in}$ ). Style $L$ halfrack package.
Model RM-3F. Rack ears with handles to mount style L full-rack instrument package in standard $31 / 2^{\prime \prime}$ rack space
Model RM-3H. Rack mounting hardware to mount either one of two Style L half-rack unit(s) in standard $31 / 2^{\prime \prime}$ rack space
DRC-Precision Option: Custom-programmed read-only-memory for DRC instruments which improves specified accuracy to $\pm 0.1 \mathrm{~K}$ or better over a given calibration range. Any DT-500 Series Silicon Diode Sensor or PT-100 Series Platinum RTD can be utilized Requires that an appropriate calibration be purchased for the Sensor. Specify Sensor input position (A or B or 1-10 on SW-10A) to assure proper location of calibration within PROM
First calibration stored
Subsequent Calibrations stored in same PROM.
Model DT-500-DRC. Silicon Diode Temperature Sensor ( 1.5 mm diameter $\times 4.1 \mathrm{~mm}$ long). Specify response curve
Model DT-500CU-DRC-36. Silicon Diode Temperature Sensor ( 8 mm diameter $\times 3.3 \mathrm{~mm}$ thick with mounting hole). Specify response curve
Model PT-101. Platinum RTD ( 3.1 mm diameter $\times 30.5 \mathrm{~mm}$ long).
Model PT-102. Platinum RTD ( 2.0 mm diameter $\times 20.3 \mathrm{~mm}$ long).
Model PT-103. Platinum RTD ( 1.8 mm diameter $\times 12.1 \mathrm{~mm}$ long).

Specifications subject to change.


FIGURE 1.1 Model DRC-84C Digital Cryogenic Thermometer/Controller

## SECTION I

## General Information

### 1.1 Introduction

The following is a description of the DRC-84C Cryogenic Digital Thermometer/Controller. The DRC-80 Series of instruments is designed to be used with the Model DT-500-DRC and DT-500CU-DRC-36 silicon diode sensors manufactured by Lake Shore Cryotronics, Inc.

Several different diode sensor curves are designed for use with this instrument. When ordering replacement sensors, care must be taken to assure that the correct sensor curve is specified. Multiple curves are needed so that Lake Shore can assure the customer that replacement sensors will be available at any time in the future. For details, please see Section 1.4.

This controller will also use the PT-101, 102 , 103 Series of platinum resistance thermometers which are available from Lake Shore Cryotronics, Inc. The data sheet for these sensors is included in the back of this manual.

### 1.2 Description

The DRC-80 Series is comprised of completely self-contained units providing direct digital readout in Kelvin temperature units and, for the controllers, temperature control by direct analog comparison between the sensor voltage and an analog equivalent of the digital temperature set point.

The Lake Shore DRC-84C utilizes two temperature sensor technologies to achieve its wide range: Silicon diodes for the low range (1.4-330K), and platinum RTD's for higher temperatures (30-800K). Each sensor type has its own input section which contains appropriate sensor excitation sources, signal conditioning, and switching. A microprocessor in the 84 C determines the temperature based on the input section activated, the sensor signal, and the sensor-response curve stored in internal memory. Additionally, the microprocessor generates a voltage equivalent to the control set-point temperature for the sensor in use. Comparison of that voltage with the actual sensor voltage produces the error signal which is the basis of the 84C's analog control.

Each input section of the DRC-84C features dual-sensor input which enables two sensors to be used concurrently. Either sensor can be selected to be the control sensor and/or the temperature display sensor (both sensors must be of the same type - silicon diodes or platinum RTD's). Thus control can be centered at one point in a system and temperature monitored elsewhere. This permits, for instance, maintenance of temperature at a particular cold stage and simultaneous measurement of sample temperature. Selection of input section as well as display and control sensor is made via front-panel pushbuttons.

A 4-digit display clearly and unambiguously shows the temperature directly in Kelvin or Celsius with 0.1 degree resolution. At low temperatures (under 30K) a SCALE EXPAND mode increases resolution to 0.01K for monitoring trends and other relative temperature measurements. Absolute accuracy at low temperatures is $\pm 0.5 \mathrm{~K}$ in either mode.

The silicon-diode input section of the DRC-84C is designed to use proven Lake Shore DT-500 Series DRC-curve silicon-diode Sensors, which provide measurement accuracy to $\pm 0.5 \mathrm{~K}$ at low temperatures. Accuracy can be increased to better than $\pm 0.1 \mathrm{~K}$ through use of an individually calibrated sensor and the DRC-Precision option to store the calibration. Any DT-500 Sensor can be utilized in the latter case.

Lake Shore PT-100 Series 100 -ohm Platinum RTD's are the ideal Sensors for the platinum section. The standard response curve is based on $0.1 \%$ interchangeability at $0^{\circ} \mathrm{C}$ and a temperature coefficient ( 0 to $100^{\circ} \mathrm{C}$ ) of $0.00835 /^{\circ} \mathrm{C}$. The curve conforms to DIN standard 43760 and is published in the Lake Shore PT-100 Technical Data sheet. Custom calibrations are available and can be incorporated into the 84 C via the DRC-Precision option.

Since silicon-diode sensors can be damaged by exposure to temperatures above 380 K (DT-500DRC Sensors should not be used above 330 K to prevent deterioration of their epoxy seals), precautions are recommended in designing systems for operation at higher temperatures. The preferred approach is to have diode sensors installed only when the system is operated below room temperature. Special software limits and error codes are generated if the instrument is set to control a point above or below the silicon diode or platinum sensor temperature limits (see Section 3.13- Table of Error Conditions).

Control temperature is easily selected and read directly in Kelvin or Celsius on front-panel digital thumbwheel switches and an adjoining scaleselect switch. The switches provide quick and constant display of the set point with a resolution of 0.1 K or ${ }^{\circ} \mathrm{C}$. Temperature controllability is a function of system design; and performance is often better than 0.1 degree.

Both the gain and reset are variable, and can be set from the front panel to enable the Controller to be precisely tuned to match the system response over any temperature region. Ample gain and reset have been designed in to assure fast response, low offset error, and high stability.

Two heater output levels are selectable on the DRC-84C. Th HI mode provides up to 25 watts of heater power while the $L 0$ mode limits output power to a nominal 10 watts.

Five options are available with the DRC-80 Series of instruments. One option is an analog signal which is proportional to temperature (DRC8-L/A). This option has a sensitivity of $10 \mathrm{mV} / \mathrm{K}$.

A second option is a ten-position switch (SW-10A) for multiple sensor readout. This switch is a separate half-rack box which plugs into the Sensor "B" position of the DRC-84C. The sensor selected is also identified via digital interface of the $D R C-84 C$, if present.

Another option is a custom cut PROM (DRC-Precision Option) which corresponds to the calibration curve of the customer's DT-500 Series sensor. A combination of a calibration and custom cut PROM will increase display accuracy to nearly $\pm .1$ Kelvin over the calibrated range. Please note that any sensor may be used with this option, i.e., the customer is not restricted to the DRC Series sensors.

There are two programming options available; each will control the set-point, the gain and reset as well as output the displayed temperature and sensor selected from the $S W-10 A$. The $D R C 8-B C D-I / O$ is in a parallel BCD format while the DRC8-IEEE is in the popular IEEE-488 format.

The DRC-80 Series is designed around a 3870 microprocessor and associated support circuits. The DRC curve is stored in a PROM which can handle up to 32 break points per curve. The data consists of a table of temperature and voltage associated with each break point. These straight line segments can generate the DRC curve to an accuracy of better than 0.1 Kelvin over the entire temperature range ( $4.0-400 \mathrm{~K}$ ). The DRC diodes match this curve to $\pm 0.5 \mathrm{~K}$ at Helium and Nitrogen temperatures and to $\pm 1.0 \mathrm{~K}$ at room temperature.

### 1.3 Major Assemblies Supplied

The DRC-84C includes as standard equipment, in addition to the digital thermometer-controller, the following:
A. Operating and Servicing Manual
B. Four five Pin Plugs for Temperature Sensor Cables
C. One seven Pin Plug for Monitor of Sensor Output Voltage and the DRC8-L/A option

Model DT-500 Series silicon diodes or platinum thermometers are not supplied as part of the DRC-84C instrument.

Complete Specifications, Accessory Equipment and Customs Options are listed in the front of the Manual.
1.4 Ordering of Replacement or Additional Sensors

Two different sensor configurations are available for use with the Model DRC-80 Series instruments. These are the DT-500-DRC and the DT-500CU-DRC-36 sensors. Their description is included elsewhere in this manual. All sensor configurations are available if the diode is calibrated and a special PROM is cut.

More than one curve presently exists which can be used with the DRC-80 Series instruments. If additional sensors are ordered for use with your instrument, you must be certain to order the correct curve so that your
instrument will have its stated accuracy. The proper curve may be determined in one of the following ways:
A. Specify the sensor serial number that is currently being used with the instrument (serial number is found on the end of the plastic box in which the sensor was received).
B. Specify the serial number of your instrument. Our records will indicate with which sensor the instrument is compatible.
C. Remove the top of your instrument and observe the indicator on the curve PROM.
D. The fourth way is to measure the diode voltage at 4.2 K and give this value to Lake Shore Cryotronics, Inc. when reordering sensors.

Lake Shore PT-100-ohm Platinum RTD's are available for the platinum section. These thermometers have a $0.1 \%$ interchangeability at $0^{\circ} \mathrm{C}$ and a temperature coefficient ( 0 to $100^{\circ} \mathrm{C}$ ) of $0.00385 /{ }^{\circ} \mathrm{C}$.

# SECTION 

Installation

### 2.1 Introduction

This section contains information and instructions necessary for the installation and shipping of the model DRC-84C Cryogenic Temperature Indicator and Controller. Included are initial inspection instructions, power and grounding requirements, installation information and instructions for repackaging for shipment.

### 2.2 Initial Inspection

This instrument was electrically and mechanically inspected prior to shipment. It should be free from mechanical damages, and in perfect working order upon receipt. To confirm this, the instrument should be inspected visually for obvious damage upon receipt and tested electrically by use to detect any concealed damage. Be sure to inventory all components supplied before discarding any shipping materials. If there is damage to the instrument in transit, be sure to file appropriate claims with the carrier, and/or insurance company. Please advise the company of such filings. In case of parts' shortages, please advise the company. The standard Lake Shore Cryotronics warranty is given on the title page.

### 2.3 Power Requirements

Before connecting the power cable to line voltage, insure that the instrument is of the proper line voltage and fused accordingly. The line voltage and fuse are shown on the rear panel of the instrument.

The line voltage can be changed by switching line voltage selector switch (S2 - Figure 6.5 DRC-84C Component Layout) located on the main printed circuit board of the unit.

Nominal permissible line voltage fluctuation is $\pm 10 \%$ at 50 to 60 Hz .

### 2.4 Grounding Requirements

To protect operating personnel, the National Electrical Manufacturer's Association (NEMA) recommends, and some local codes require, instrument panels and cabinets to be grounded. This instrument is equipped with a threeconductor power cable which, when plugged into an appropriate receptacle, grounds the instrument.

### 2.5 Installation

The DRC-84C Thermometer/Controller is all solid state and does not generate significant heat. It may therefore be rack mounted in close proximity to other equipment in dead air spaces. The heat from such adjacent equipment should not subject the controller to an ambient temperature in excess of
$50^{\circ} \mathrm{C}\left(122^{\circ} \mathrm{F}\right)$. As with any precision instrument, it should not be subjected to the shock and vibrations which usually accompany high vacuum pumping systems.

The recommended cable diagrams for the sensor diode and heater element (in the case of the DRC-84C controllers) are shown in Figure 2.1 (a) and (b). The use of a four wire diode or resistor connections is highly recommended to avoid introducing lead IR drops which will occur if the alternate two lead sensor cable connection is used. For example, for a two lead connection with diodes, every 25 ohms of cable resistance corresponds to a . 1 K error above 30 Kelvin. The alternate wiring scheme shown in Figure 2.1 (c) may be used for the diode in less critical applications where lead resistance can be kept small. Because of the low resistance of platinum resistance thermometers, the four lead cable connections must be used to obtain system accuracy. The indicated shielding connections are the recommended standard practice to avoid ground loops. Figure 2.1 (d) shows the monitor connections for the analog output of sensor voltage ( $0-2.5 \mathrm{~V}$ for diodes, $0-3.0 \mathrm{~V}$ for $\mathrm{platinum} ,\mathrm{Pin} \mathrm{A)} \mathrm{and}$ optional linear analog output of temperature ( $0-8 \mathrm{~V}$, Pin C ). In the case of the platinum resistor, the buffered output voltage is -20 times the actual sensor voltage. For example, if the input voltage from the platinum sensor is 0.0100 V , then the buffered output voltage would be -0.2000 V .

### 2.6 Repackaging for Shipment

Before returning an instrument to the factory, should repair be necessary, please discuss the malfunction with a factory representative. He may be able to suggest several field tests which will preclude returning a satisfactory instrument to the factory when the malfunction is elsewhere. If it is indicated that the fault is in the instrument after these tests, the representative will provide shipping and labeling instructions for returning it.

When returning an instrument, please attach a tag securely to the instrument itself (not on the shipping carton) clearly stating:
A. Owner and Address
B. Instrument Model and Serial Number
C. Malfunction Symptoms
D. Description of External Connections and Cryostats

If the original carton is available, repack the instrument in a plastic bag, place in carton using original spacers to protect protruding controls, and close carton. Seal lid with paper or nylon tape. Affix mailing labels and "FRAGILE" warnings.


Do not ground shield

(D) MONITOR OUTPUT

## Operating Instructions

### 3.1 Introduction

This section contains a description of the operating controls and their adjustment under normal operating conditions, and typical controller applications. These instructions are based upon the instrument having been installed as outlined in Section II. The diode polarity as shown in Figure 2.1 (a), in particular, must be correct. For the DRC-84C instrument, a 25 ohm heating element is assumed attached to the "Heater" terminals as shown in Figure 2.1 (b).

### 3.2 Controls, Indicators, Connectors

The operating controls, indicators and connectors on the DRC-84C instrument's front and rear panels are shown in Figures 3.1, and 3.2. The numbers with leaders to various controls in the figures are keyed to the entries in Table 3.1.

Table 3.1 - Entry Number Correlation

| NO. KEY | NAME | FUNCTION |
| :---: | :---: | :---: |
| 1 | POWER | A.C. Iine switch (ON/OFF) (Display serves as indicator light). |
| 2 | NO LABEL | Digital set point. Has 0.1 K resolution. |
| 3 | Gain | Variable gain allows adjustment of overall controller gain over 100 to 1 range. Maximum gain is full clockwise prior to detent position labeled REM which transfers gain control to remote $B C D$ or IEEE option when present. The potentiometer is logarithmic so that $x 10$ gain is approximately one-half of full rotation. |
| 4 | Reset | Adjusts reset time constant of integrator. Effectively determines time constant of integrator between 25 and 1 seconds, minimum and maximum, respectively. Note that reset control can be transferred to either the BCD or IEEE options if one of them is present. |
| 5 | NO LABEL | Digital temperature display located behind filter panel. LED indicators also indicate scale expand, which sensor is selected for display, which sensor is selected for control and type of sensor. |

This Page Intentionally Left Blank

| 6 | Scale Expand | With button out, the display reads to 0.1 K at all temperatures; with button in detent position, temperature reads to 0.01 K below $30 \mathrm{~K}, 0.05 \mathrm{~K}$ between 30 K and 100 K , and to 0.1 K above 100 K . Scale expand is indicated ori display pariel. |
| :---: | :---: | :---: |
| 7 | Sensor Display | With button out, serisor A temperature is displayed; with button in detent position, sensor $B$ is read and displayed. Sensor being read is also indicated on display pariel. |
| 8 | Serisor Control | With button out, sensor $A$ is control sensor; with buttor in detert position, sensor $B$ is the control sensor. Control sensor is also indicated on display panel. |
| 9 | Type | With button out, the silicon diode inputs are selectable; with button in detent position, the platinum sensor inputs are selected. |
| 10 | Heater Power | With button out, heater power maximum is 10 watts (LO); in detent position, full heater power is available ( 25 watts). |
| 11 | HI | Hi power LED indicator. |
| 12 | Scale | Selects either the Celsius or Kelvin scale for both the display and the set-point. |
| 13 | NO LABEL | A.C. line cord. |
| 14 | Fuse | A.C. line fuse. |
| 15 | Diode Serisor Inputs | Diode Sensor $A$ and $B$ input lead terminals (Pin A, $I_{+}, \operatorname{Pin} E, V_{+}, \operatorname{Pin} B, I-, \operatorname{Pin} D$, $\mathrm{V}-$, Pin H , Shield). |
| 16 | Platirum Sensor Inputs | Same correctioris as for diode sersors. |
| 17 | Monitor | Aralog output of sensor voltage ( $0-2.5 \mathrm{~V}$, pin A) and optional linear analog output of temperature ( $0-4 \mathrm{~V}$, pin C ). Pin $B$ is ground for sersor voltage, Pin $D$ is ground for linear analog output. |



FIGURE 3.1 DRC-84C Front Panel


| 18 | Heater | Heater element terminals (25 ohm heater <br> required for 25 watts of power). |
| :---: | :--- | :--- |
| 19 | Fuse | Output power fuse (1.0 ASB specified). <br> 20 Interface |
| BCD input of set point, gain and reset <br> output of temperature. Also IEEE <br> interface port. |  |  |
| 21 | GND | Instrument or case ground |

### 3.3 Temperature Readout

The sensor(s) and heater should be installed following the suggestions listed in the "Installation and Application Notes for Cryogenic Sensors" brochure in Section VIII.

Connect the sensor(s) to the instrument following the diagram in Figure 2.1.

Depress the power switch and observe that the display shows the proper temperature relative to the sample temperature.

If the diode or lead wires are shorted or if the diode is connected backwards, the display will read (---) and flash 428.0. In the case of an open current or voltage lead, the display will slowly drift higher in temperature from the last voltage reading taken by the $A / D$ converter.

The sensor and readout display for diodes should follow Table 3.4 which illustrates typical values expected of the standard DT-500-DRC or DT-500CU-DRC-36sensors for your appropriate curve.

The DIN standard curve for the platinum sensors is given in Table 3.7.
If the instrument or sensor does not agree with values listed in the table, within the accuracy of the system, consult sections on installation and/or section on troubleshooting to determine the cause and cure of the malfunction. If an error code is displayed, refer to Section 3.13 for possible corrections.

### 3.4 Analog Control

The digital set point of temperature is converted to analog set point of voltage which is then compared to the sensor voltage by summing two respective currents of opposite sign.

To familiarize yourself with the DRC-84C control section, set the instrument so that you are reading and controlling with the same sensor. Turn the reset (integral) control section off. Establish a set point temperature several degrees above the display temperature. Gradually turn the gain clockwise from a minimum position. Note that as the gain is increased, the offset between the display temperature and the set point
will be decreased. The gain potentiometer is logarithmic with rotation and covers a 100 to 1 range so that the gain at mid-rotation is ten times the minimum gain.

With most systems, an oscillation in temperature will occur at some clockwise rotation. Further clockwise rotation will cause a wild oscillation in temperature. The gain should then be backed off until a stable control temperature occurs. Note that an offset between display temperature and set point will still be present.

Finally, turn on the reset control. With the addition of reset, the temperature error between setpoint and control temperature should reduce to zero. The rate at which this reduces to zero is determined again by a clockwise rotation with the shortest time constant occurring at full clockwise rotation.

Note that the system can become unstable again with too much reset added. Slight variations in the gain and/or reset should give stable temperature control.

The HI-LO power switch also changes the loop gain with the HI position increasing the gain by a factor of approximately two. It may be necessary when changing from $L O$ to $H I$ power setting to reduce the gain slightly to compensate for the increased overall loop gain.

### 3.5 Analog Output of Temperature

The analog output of temperature takes the display temperature and converts it to an analog signal which has a sensitivity of $10 \mathrm{mV} / \mathrm{K}$ under normal operation. The analog output voltage is located on the monitor connector (Key 17 of Figure 3.2). See Section 3.10 for installation notes on DRC-8-L/A.
3.6 Standard DT-500-DRC and DT-500CU-DRC-36 Curves

The standard DT-500-DRC and DT-500CU-DRC-36 curve is explained in Section 3.3. The Tables include a list of PROM sensor voltages and breakpoints used in the linearization of the DRC curve to arrive at the correct temperature readout.

### 3.7 The 10-Sensor Selector Switch

The 10-Sensor Selector Switch includes an umbilical which ties to the DRC-84C main printed circuit board (via a 16 -pin ribbon cable header which plugs into internal socket JC (see Figure 6.5, DRC-84C Component Layout) and a cable to connect the selected sensor leads to the DRC-84C (Sensor Plug B is either Key 15 or Key 16 of Figure 3.2).

The SW-10A is supplied with an $18^{\prime \prime}$ cable which is shielded and has male 5-pin amphenol connectors at each end. This cable connects between

J11 of the SW-10A and one of the $B$ sensor plugs of the DRC-84C. Sensors are connected to the SW-10A via printed circuit edge J10. A $36-\mathrm{pin}$ edge card connector and hood has been supplied with the $S W-10 A$. Connectors to this edge J10 are given in Table 3.5.

### 3.8 Remote Parallel BCD Input/Output Option

The $B C D$ option consists of a 16 bit parallel output of temperature along with a scale expand bit to indicate decimal point, a 15 bit parallel input of set point in Kelvin degrees or Celsius (depending on switch position), a 4 bit parallel input of gain setting, a 4 bit parallel input of reset setting, and a 4 bit output of switch position from the SW-10A.

Table 3.6 can be used for input and output line coding.

The $B C D$ in and out is handled through connector $J 4$ (denoted on back panel as INTERFACE), a 50 pin connector on the rear panel of the instrument. Two internal jumper wires are placed on the printed circuit board in front of internal connector JE. Cutting these jumpers allows the user to enable the remote set point by setting Pin 38 , J4 high (see Table 3.6). If the option was installed prior to shipment, these jumpers have already been cut. Options that are field installed need to have their jumpers cut by the user.

Data latches internal to the instrument provide a $1-2-4-8$ code using positive logic with standard TTL levels of 0.4 volts or less for low (logic 0 ) and 2.4 volts or higher for the high (or 1) state under full load conditions. The drivers are sufficient to drive two standard loads, 3.2 mA , in the low state.

Set point is input to the instrument via a remote set point enable pin (externally generated, pin 38). With no connection made to the external enable pin, the option selects the internal (front panel) set point. When the unit is receiving a set point externally, the front panel set point switches are disabled.

The sensor temperature output is externally gated through the use of an internally generated data valid pulse.

Input of gain value and reset can be seen in the following tables (highs are denoted as "l" and lows are denoted as "O").

Table 3.2

## Relative Gain for BCD Option

GAIN

| Piri | Pin | Pin | Pin | Relative Gain* |
| :---: | :---: | :---: | :---: | :---: |
| 48 | 46 | 44 | 42 |  |
| 0 | 0 | 0 | 0 | Min. |
| 0 | 0 | 0 | 1 | 2. |
| 0 | 0 | 1 | 0 | 2.5 |
| 0 | 0 | 1 | 1 | 3.25 |
| 0 | 1 | 0 | 0 | 3.85 |
| 0 | 1 | 0 | 1 | 4.8 |
| 0 | 1 | 1 | 0 | 5.2 |
| 0 | 1 | 1 | 1 | 6.1 |
| 1 | 0 | 0 | 0 | 13.3 |
| 1 | 0 | 0 | 1 | 14.2 |
| 1 | 0 | 1 | 0 | 14.5 |
| 1 | 0 | 1 | 1 | 15.4 |
| 1 | 1 | 0 | 0 | 15.8 |
| 1 | 1 | 0 | 1 | 16.65 |
| 1 | 1 | 1 | 0 | 17.2 |
| 1 | 1 | 1 | 1 | Max. |

*The gain of the basic instrument is 10 to 1000 with the front panel potentiometer covering a 100:1 span. The relative gain is the gain factor above which the base instrument has incorporated. These relative gains can be multiplied by about 10 to get overall gain.

These values were determined to make use of the range of gain most used and the fact that the circuit is based on a negative logarithmic variation of the front panel potentiometer.

This table can be shifted up or down in terms of overall gain if the customer rieeds to, but should not be recessary.

The reset amplifier readings take on roughly the same sort of plot as the gain with minimum reset value with all lines low and maximum reset value with all lines high.

Table 3.3
Reset Time Constants for BCD Option

RESET:

| Pin | Pin | Pin | Pin |  |
| :---: | :---: | :---: | :---: | :---: |
| 47 | 45 | 43 | 41 | (sec) |
| 0 | 0 | 0 | 0 | Off (Open) |
| 0 | 0 | 0 | 1 | 28 |
| 0 | 0 | 1 | 0 | 21 |
| 0 | 0 | 1 | 1 | 19 |
| 0 | 1 | 0 | 0 | 16 |
| 0 | 1 | 0 | 1 | 14 |
| 0 | 1 | 1 | 0 | 12 |
| 0 | 1 | 1 | 1 | 10 |
| 1 | 0 | 0 | 0 | 9 |
| 1 | 0 | 0 | 1 | 8 |
| 1 | 0 | 1 | 0 | 7 |
| 1 | 0 | 1 | 1 | 6 |
| 1 | 1 | 0 | 0 | 5 |
| 1 | 1 | 0 | 1 | 4 |
| 1 | 1 | 1 | 0 | 3 |
| 1 | 1 | 1 | 1 | Min. |

Table 3.4

DT-500DRC (D) Voltage-Temperature Characteristic

| BP\# | TEMP (K) | PROM VOLTAGE |
| :---: | :---: | :---: |
|  | 1.4 | 2.5984 |
|  | 1.5 | 2.5958 |
|  | 1.6 | 2.5932 |
|  | 1.7 | 2.5906 |
|  | 1.8 | 2.5880 |
| 30 | 1.9 | 2.5854 |
|  | 2.0 | 2.5828 |
|  | 2.2 | 2.5735 |
|  | 2.4 | 2.5643 |
|  | 2.6 | 2.5551 |
| 29 | 2.8 | 2.5458 |
|  | 3.0 | 2.5366 |
|  | 3.2 | 2.5226 |
|  | 3.4 | 2.5086 |
|  | 3.6 | 2.4946 |
|  | 3.8 | 2.4807 |
|  | 4.0 | 2.4667 |
|  | 4.2 | 2.4527 |
|  | 4.4 | 2.4387 |
|  | 4.6 | 2.4247 |
|  | 4.8 | 2.4108 |
|  | 5.0 | 2.3968 |
|  | 5.5 | 2.3618 |
|  | 6.0 | 2.3269 |
|  | 6.5 | 2.2919 |
| 28 | 7.0 | 2.2570 |
|  | 7.5 | 2.2220 |
|  | 8.0 | 2.1871 |
|  | 8.5 | 2.1521 |
|  | 9.0 | 2.1172 |
| 27 | 9.5 | 2.0909 |
|  | 10.0 | 2.0646 |
|  | 11.0 | 2.0119 |
|  | 12.0 | 1.9592 |
|  | 13.0 | 1.9066 |
| 26 | 14.0 | 1.8338 |
|  | 15.0 | 1.7610 |
|  | 16.0 | 1.6984 |
| 25 | 17.0 | 1.6359 |
|  | 18.0 | 1.5646 |

DT-500DRC (D) Voltage-Temperature Characteristic

| BP\# | TEMP (K) | PROM VOLTAGE |
| :---: | :---: | :---: |
|  | 19.0 | 1.4932 |
|  | 20.0 | 1.4219 |
| 24 | 21.0 | 1.3505 |
|  | 22.0 | 1.3006 |
| 23 | 23.0 | 1.2507 |
|  | 24.0 | 1.2114 |
| 22 | 25.0 | 1.1720 |
| 21 | 26.0 | 1.1486 |
| 20 | 27.0 | 1.1308 |
| 19 | 28.0 | 1.1190 |
| 18 | 29.0 | 1.1116 |
| 17 | 30.0 | 1.1058 |
| 16 | 32.0 | 1.0970 |
| 15 | 34.0 | 1.0902 |
|  | 36.0 | 1.0850 |
| 14 | 38.0 | 1.0798 |
|  | 40.0 | 1.0746 |
|  | 45.0 | 1.0633 |
|  | 50.0 | 1.0520 |
| 13 | 55.0 | 1.0407 |
| 12 | 60.0 | 1.0287 |
|  | 65.0 | 1.0166 |
|  | 70.0 | 1.0046 |
|  | 75.0 | 0.99172 |
|  | 80.0 | 0.97890 |
| 11 | 85.0 | 0.96609 |
|  | 90.0 | 0.95327 |
|  | 95.0 | 0.93987 |
|  | 100.0 | 0.92647 |
|  | 105.0 | 0.91307 |
| 10 | 110.0 | 0.89966 |
|  | 115.0 | 0.88626 |
|  | 120.0 | 0.87286 |
|  | 125.0 | 0.85946 |
|  | 130.0 | 0.84606 |
|  | 135.0 | 0.83228 |
|  | 140.0 | 0.81850 |
|  | 145.0 | 0.80472 |
|  | 150.0 | 0.79094 |
|  | 155.0 | 0.77716 |
|  |  |  |


| BP\# | TEMP (K) | PROM VOLTAGE |
| :---: | :---: | :---: |
| 9 | 160.0 | 0.76338 |
|  | 165.0 | 0.74961 |
|  | 170.0 | 0.73582 |
|  | 175.0 | 0.72170 |
|  | 180.0 | 0.70757 |
|  | 185.0 | 0.69344 |
|  | 190.0 | 0.67931 |
|  | 195.0 | 0.66518 |
|  | 200.0 | 0.65105 |
|  | 205.0 | 0.63693 |
| 8 | 210.0 | 0.62280 |
|  | 215.0 | 0.60867 |
|  | 220.0 | 0.59455 |
|  | 225.0 | 0.58080 |
|  | 230.0 | 0.56707 |
| 7 | 235.0 | 0.55334 |
|  | 240.0 | 0.53960 |
|  | 245.0 | 0.52649 |
|  | 250.0 | 0.51337 |
|  | 255.0 | 0.50026 |
| 6 | 260.0 | 0.48714 |
|  | 265.0 | 0.47403 |
|  | 270.0 | 0.46057 |
|  | 275.0 | 0.44711 |
|  | 280.0 | 0.43365 |
| 5 | 285.0 | 0.42019 |
|  | 290.0 | 0.40613 |
|  | 295.0 | 0.39208 |
|  | 300.0 | 0.37802 |
| 4 | 305.0 | 0.36397 |
|  | 310.0 | 0.34940 |
|  | 315.0 | 0.33482 |
|  | 320.0 | 0.32025 |
|  | 325.0 | 0.30568 |
|  | 330.0 | 0.29111 |
| 3 | 335.0 | 0.27654 |
|  | 340.0 | 0.26197 |
|  | 345.0 | 0.24739 |
|  | 350.0 | 0.23325 |
|  | 355.0 | 0.21911 |
| 2 | 360.0 | 0.20497 |
|  | 365.0 | 0.19083 |
|  | 370.0 | 0.17774 |
|  | 375.0 | 0.16464 |
| 1 | 380.0 | 0.15155 |
|  |  |  |

Table 3.5

SW-10A CONNECTOR DETAIL

| Function | Sensor | Edge Connector Contact |
| :---: | :---: | :---: |
| Shield | A11 | 1 |
| I- | A11 | 2 |
| V+ | 1 | A |
| V- | 1 | B |
| I+ | 1 | 3 |
| V+ | 2 | C |
| V- | 2 | D |
| I+ | 2 | 4 |
| V+ | 3 | E |
| V- | 3 | F |
| I+ | 3 | 5 |
| V+ | 4 | H |
| v- | 4 | J |
| I+ | 4 | 6 |
| V+ | 5 | K |
| V- | 5 | L |
| I+ | 5 | 7 |
| V+ | 6 | M |
| v- | 6 | N |
| I+ | 6 | 8 |
| V+ | 7 | P |
| V- | 7 | R |
| I+ | 7 | 9 |
| V+ | 8 | S |
| V- | 8 | T |
| I+ | 8 | 10 |
| V+ | 9 | U |
| V- | 9 | v |
| I+ | 9 | 11 |
| V+ | 10 | 17 |
| $\mathrm{V}-$ | 10 | 18 |
| I+ | 10 | 12 |

Table 3.6

BCD TEMPERATURE OUTPUT - MODEL DRC-SERIES REMOTE I/O

```
\dot{2}
\dot{1}
```

| BCD | TEMPERATURE OUTPUT |  | TEMPERATURE POINT INPUT |
| :---: | :---: | :---: | :---: |
| PIN |  | PIN |  |
| 1 | 800 | 2 | . 1 |
| 3 | 400 | 4 | . 2 |
| 5 | 200 | 6 | . 4 |
| 7 | 100 | 8 | . 8 |
| 9 | 80 | 10 | 1 |
| 11 | 40 | 12 | 2 |
| 13 | 20 | 14 | 4 |
| 15 | 10 | 16 | 8 |
| 17 | 8 | 18 | 10 |
| 19 | 4 | 20 | 20 |
| 21 | 2 | 22 | 40 |
| 23 | 1 | 24 | 80 |
| 25 | . 8 | 26 | 100 |
| 27 | . 4 | 28 | 200 |
| 29 | . 2 | 30 | SW-BO |
| 31 | . 1 | 32 | SW-B1 |



Table 3.7

DIN Standard Curve for Platinum Sensors

| BP\# | TEMP (K) | RES (OHMS) |
| :---: | :---: | :---: |
| 28 | 30.0 | 3.82000 |
| 27 | 32.0 | 4.23481 |
|  | 34.0 | 4.68000 |
| 26 | 36.0 | 5.14601 |
|  | 38.0 | 5.65000 |
| 25 | 40.0 | 6.17000 |
| 24 | 42.0 | 6.72621 |
|  | 44.0 | 7.31000 |
| 23 | 46.0 | 7.90899 |
|  | 48.0 | 8.57000 |
|  | 50.0 | 9.24000 |
| 22 | 52.0 | 9.92364 |
|  | 54.0 | 10.66000 |
|  | 56.0 | 11.41000 |
| 21 | 58.0 | 12.17995 |
|  | 60.0 | 12.99000 |
| 20 | 65.0 | 15.01541 |
|  | 70.0 | 17.11000 |
| 19 | 75.0 | 19.22302 |
|  | 80.0 | 21.36000 |
| 18 | 85.0 | 23.52499 |
|  | 90.0 | 25.67000 |
|  | 95.0 | 27.82000 |
|  | 100.0 | 29.95000 |
| 17 | 105.0 | 32.08087 |
|  | 110.0 | 34.16000 |
|  | 115.0 | 36.25000 |
|  | 120.0 | 38.34000 |
|  | 125.0 | 40.42000 |
|  | 130.0 | 42.49000 |
| 16 | 135.0 | 44.57000 |
|  | 140.0 | 46.64758 |
|  | 145.0 | 48.69000 |
|  | 150.0 | 50.75000 |
|  | 155.0 | 52.80000 |
| 15 | 160.0 | 54.84000 |
|  | 165.0 | 56.88000 |
|  | 170.0 | 58.92000 |
|  | 175.0 | 60.96840 |
|  | 180.0 | 62.98000 |
|  |  |  |


| BP\# | TEMP (K) | RES (OHMS) |
| :---: | :---: | :---: |
|  | 185.0 | 65.00000 |
|  | 190.0 | 67.01000 |
|  | 195.0 | 69.02000 |
|  | 200.0 | 71.03000 |
|  | 205.0 | 73.03000 |
| 14 | 210.0 | 75.04385 |
|  | 215.0 | 77.02000 |
|  | 220.0 | 79.00000 |
|  | 225.0 | 80.98000 |
|  | 230.0 | 82.96000 |
|  | 235.0 | 84.94000 |
|  | 240.0 | 86.92000 |
|  | 245.0 | 88.90000 |
|  | 250.0 | 90.88000 |
|  | 255.0 | 92.86000 |
| 13 | 260.0 | 94.83000 |
|  | 265.0 | 96.80000 |
|  | 270.0 | 98.78433 |
|  | 275.0 | 100.72000 |
|  | 280.0 | 102.67000 |
|  | 285.0 | 104.62000 |
|  | 290.0 | 106.57000 |
|  | 295.0 | 108.51000 |
|  | 300.0 | 110.45000 |
|  | 305.0 | 112.39000 |
| 12 | 310.0 | 114.32000 |
|  | 315.0 | 116.27003 |
|  | 320.0 | 118.19000 |
|  | 325.0 | 120.11000 |
|  | 330.0 | 122.03000 |
| 11 | 335.0 | 123.95000 |
|  | 340.0 | 125.86000 |
|  | 345.0 | 127.78000 |
|  | 350.0 | 129.69000 |
|  | 355.0 | 131.61563 |
|  | 360.0 | 133.50000 |
|  | 365.0 | 135.40000 |
|  | 370.0 | 137.31000 |
|  | 375.0 | 139.20000 |
|  | 380.0 | 141.09000 |
|  |  |  |



| BP\# | TEMP (K) | RES (OHMS) |
| :---: | :---: | :---: |
| 6 | 585.0 | 216.25553 |
|  | 590.0 | 218.01000 |
|  | 595.0 | 219.78000 |
|  | 600.0 | 221.55000 |
|  | 605.0 | 223.31000 |
| 5 | 610.0 | 225.07000 |
|  | 615.0 | 226.83000 |
|  | 620.0 | 228.59000 |
|  | 625.0 | 230.34000 |
|  | 630.0 | 232.10593 |
|  | 635.0 | 233.84000 |
|  | 640.0 | 235.57000 |
|  | 645.0 | 237.31000 |
|  | 650.0 | 239.06000 |
|  | 655.0 | 240.79000 |
| 4 | 660.0 | 242.52000 |
|  | 665.0 | 244.25000 |
|  | 670.0 | 245.97000 |
|  | 675.0 | 247.71350 |
|  | 680.0 | 249.42000 |
|  | 685.0 | 251.14000 |
|  | 690.0 | 252.85000 |
|  | 695.0 | 254.56000 |
|  | 700.0 | 256.27000 |
|  | 705.0 | 257.97000 |
| 3 | 710.0 | 259.68000 |
|  | 715.0 | 261.39092 |
|  | 720.0 | 263.07000 |
|  | 725.0 | 264.77000 |
|  | 730.0 | 266.46000 |
| - | 735.0 | 268.14000 |
|  | 740.0 | 269.83000 |
|  | 745.0 | 271.51000 |
|  | 750.0 | 273.19000 |
|  | 755.0 | 274.87000 |
| 2 | 760.0 | 276.56633 |
|  | 765.0 | 278.22000 |
|  | 770.0 | 279.88000 |
|  | 775.0 | 281.55000 |
|  | 780.0 | 283.21000 |
| 1 | 785.0 | 284.87000 |
|  | 790.0 | 286.53000 |
|  | 795.0 | 288.18000 |
|  | 800.0 | 289.83000 |
|  |  |  |
|  |  |  |

The IEEE interface option available for the DRC instruments fully complies with the IEEE standard 488-1978 and incorporates the functional, electrical and mechanical specifications of the standard.

### 3.9.1 Genera1 IEEE Specifications and Operation

The following discussion covers the general operation of the IEEE-488 interface. For a more detailed description of signal level and interaction, refer to the IEEE Std. 488-1978 publication "IEEE Standard Digital Interface for Programmable Instrumentation".

All instruments on the interface bus must be able to perform the interface functions of TALKER, LISTENER, or CONTROLLER. A TALKER transmits data onto the bus to other devices. A LISTENER receives data from other devices through the bus. Some devices perform both functions. The CONTROLLER designates to the devices on the bus which function to perform.

The IEEE works on a party line basis with all devices on the bus connected in parallel. All the active circuitry of the bus is contained within the individual devices with the cable connecting all the devices in parallel to allow the transfer of data between all devices on the bus.

There are 16 signal lines contained on the bus:
A) 8 Data Lines
B) 3 Byte Transfer Control Lines
C) 5 General Interface Management Lines

The data lines consist of 8 signal lines that carry data in a bit parallel, byte serial format. These lines carry universal commands, addresses, program data, measurement data, and status to all the devices on the bus. The controller designates the functions of the units on the bus by setting the ATN line low (true) and sending talk or listen addresses on the DATA lines. When the ATN line is low, all devices listen to the DATA lines. When the ATN line goes high (false), then the devices addressed to send or receive data perform their functions while all others ignore the DATA lines.

Transfer of the information on the data lines is accomplished through the use of three signal lines: DAV (Data Valid), NRFD (Not Ready For Data), and NDAC (Not Data Accepted). These signals operate in an interlocking handshake mode. The two signal lines, NRFD, and NDAC are each connected in a logical AND to all devices connected to the bus. The DAV is sent by the talker and received by listeners while the NRFD and NDAC are sent by listeners back to the talker.

The General Interface Management Lines manage the bus and control the orderly flow of commands on the bus. The IFC (Interface Clear) message
basically clears the interface to a known state appropriate to the device being addressed. SRQ (Service Request) is used by a device to indicate the need for attention or service and to request an interruption of data flow. REN (Remote Enable) is used to select between two sources of device data (an an example: front panel or rear panel controls on a measurement device). EOI (End or Identify) indicates the end of a multiple byte transfer sequence, or along with the ATN line, executes a polling sequence.

### 3.9.2 Specific Operation of the DRC8-IEEE Interface

The DRC8-IEEE allows for the remote control of set-point, gain and reset. It also provides a digital output of temperature in Kelvin, the present values of set-point, gain and reset, as well as the status of the front panel switches and Remote/Local status.

Address and function selection are made via a switch package located on the rear panel of the DRC instrument (see Figure 3.3 DRC8-IEEE panel layout). Positions $4-8$ of the switch are the address switches for the interface with 4 being the most significant bit and 8 being the least significant bit. As an example: with switches 5,6 , and 7 ON , and switches 4 and 8 OFF , the address selected is 14 (or E base 16). Position 3 of the switch package is the TALKER select with position 2 being the LISTENER select. Both functions are selected with both switches OFF (or up), while either can be deselected by turning the appropriate switch ON (or down).

Switch position 1 is used to select the order in which the output delimiters are put onto the IEEE bus. The following table gives the delimiter orientation versus switch position:

Switch 1 Position
Up (OFF)
Down (ON)

Delimiter Order (De1m 1)(De1m 2)
(LF) (CR)
(CR) (LF)

The use of this switch allows the DRC8-IEEE to interface to controllers which accept both forms of delimiters to terminate input strings. NOTE: the address switches are updated on power up only. The address and delimiter orientation is read only when the instrument is turned on. Any change in the address switch while the instrument is on will be ignored.

The DRC8-IEEE transmits and receives all characters in ASCII. The cable connector meets IEEE-488, 1978 standards and is polarized for proper cable insertion. The following table shows cable connector contact wiring for the IEEE-488 bus:

| Contact | Signal Line | Contact | Signal Line |
| :---: | :--- | :---: | :--- |
|  |  |  |  |
| 1 | DIO1 | 13 | DI05 |
| 2 | DIO2 | 14 | DIO6 |
| 3 | DIO3 | 15 | DI07 |
| 4 | DIO4 | 16 | DI08 |
| 5 | EOI(24) | 17 | REN(24) |
| 6 | DAV | 18 | Gnd (6) |
| 7 | NRFD | 19 | Gnd(7) |
| 8 | NDAC | 20 | Gnd(8) |
| 9 | IFC | 21 | Gnd(9) |
| 10 | SRQ | 22 | Gnd (10) |
| 11 | ATN | 23 | Gnd (11) |
| 12 | SHIELD | 24 | Gnd(LOGIC) |

Note: Gnd ( $n$ ) refers to the signal ground return of the referenced contact. EOI and REN return on contact 24.

When addressed as a TALKER, the interface outputs gain and reset settings, front panel settings (including Remote/Local status), set point and display temperature in the form of five string variables. After each one of the variables is output, delimiters DELM1 and DELM2 are transmitted. After the fifth variable, the last delimiter has the EOI line set for end.

NOTE: In programming for an input from the DRC8-IEEE interface five string variables must be used (or read into the computer) or the interface will hang up, waiting to output all of the data. In outputting data to an array, the array must have enough elements to allow the input of all five variables from the DRC8-IEEE interface (in this case the number of elements is 27). Since there are five sets of delimiters output, and most computers use these delimiters to terminate string variables, the need for five string variables arises. An example of a transmission is as follows:


Figure 3.3 DRC-84C-IEEE Panel Layout

The front panel variable has as its first character a remote/local status indicator. If the first character is a 0 , then the instrument will respond to front panel set point controls. If the character is a 1 , then the unit will respond to a set point from the IEEE interface.

The next two front panel characters are output in a packed format with individual bits representing' a piece of data. The front panel indicators are denoted as follows:

a) Bits 1-4 SW-10A Display Sensor switch positions with bit 1 being the Least Significant Bit, and bit 4 being the Most Significant Bit.

| b) | Bit 5 | Type | $\begin{aligned} & 0 \\ & 1 \end{aligned}$ | Button Out <br> Button In | (Si) <br> (Plat) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| c) | Bit 6 | Control Sensor | 0 | Button Out | (A) |
|  |  |  | 1 | Button In | (B) |
| d) | Bit 7 | Display Sensor | 0 | Button Out | (A) |
|  |  |  | 1 | Button In | (B) |
| e) | Bit 8 | Scale EXPAND Mode | 0 | Button Out | (normal) |
|  |  |  | 1 | Button In | (Expanded |

*NOTE: The expanded scale bit is set only if the button is in and the display temperature is below $100.0^{\circ} \mathrm{K}$.

A chart which shows the pushbutton information and corresponding output character is shown below. (This is data represented by the second character of the Panel information variable, or bits 5-8 above).

| Output Character | Bit Representation | Expanded Scale | Display <br> Sensor | Control <br> Sensor | Type |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0000 | no | A | A | Si |
| 1 | 0001 | no | A | A | Plat |
| 2 | 0010 | no | A | B | Si |
| 3 | 0011 | no | A | B | Plat |
| 4 | 0100 | no | B | A | Si |
| 5 | 0101 | no | B | A | Plat |
| 6 | 0110 | no | B | B | Si |
| 7 | 0111 | no | B | B | Plat |
| 8 | 1000 | yes | A | A | Si |
| 9 | 1001 | yes | A | A | Plat |
| A | 1010 | yes | A | B | Si |
| B | 1011 | yes | A | B | Plat |
| C | 1100 | yes | B | A | Si |
| D | 1101 | yes | B | A | Plat |
| E | 1110 | yes | B | B | Si |
| F | 1111 | yes | B | B | Plat |

The SW-10A switch position is represented by the characters $1-9$, and A. The 1-9 stands for positions 1 thru 9, the A stands for position 10. The switch position information is only present for the B display sensor. When the A position is selected as display sensor, the position is returned as zero. (When there is no position present for the $B$ display sensor, the switch position is returned as zero. An example of the panel information for a DRC instrument that is in remote (accepts set point commands from the IEEE), is in the expanded scale mode, has $B$ as display sensor, $A$ as control sensor, and has an SW-10A position of 2 , would look like 1C2.

When the instrument is in display A mode, the external switch position is ignored and the switch position character is set to zero.

An example of a transmission for an instrument which has: switch 1 of the IEEE address switch up at power on, a gain setting of 5 , a reset setting of $C$, scale expand button in, A as display sensor, $B$ as control sensor, no $S W-10 A$ input, set point of $130.0^{\circ} \mathrm{K}$, and a display of $24.06^{\circ} \mathrm{K}$, is in remote control (IEEE), and has Si as type would look like this:
5 (LF) (CR) C (LF) (CR) 1A0 (LF) (CR) 130.0 (LF) (CR) 0024.06 (LF) (CR) EOI SET ON FINAL (CR)

When there is a display error message, this message is transmitted over the bus in the temperature variable. The following table gives the display error and the corresponding error code output from the IEEE:

| Display Sensor | Interface Equivalent |
| :---: | :---: |
| LO 1 | E100.00 |
| HI 1 | E200.00 |
| HI 2 | E300.00 |
| LO 2 | E400.00 |

When addressed as a LISTENER, the interface must receive a code (function) and code settings to set parameters. The codes and commands along with formats are:

| CODE | FUNCTION | FORMAT FOR DATA | FORMAT LIMITS (X) |
| :---: | :---: | :---: | :---: |
| A | Set Point | Variable forms of XXX.X | only numerics accepted |
| B | Gain | X | 0-9, A-F |
| C | Reset | X | 0-9, A-G |
| D | Flag Toggle | -- | -- |

The A command allows for considerable flexibility. If the A command is received, but not followed by any numerics, the set point is set to zero. The internal program is structured so that the last three numerics before the decimal point are accepted and the first numeric after the decimal point. All other ASCII characters are ignored except for $B, C$, and $D$. The following examples should illustrate the flexibility of the input. (This format makes the allowance for the implied sign before any numeric variable output in basic programming.)

| INPUT | SET POINT |
| :--- | :--- |
| A | 000.0 |
| A9 | 009.0 |
| A8009.6 | 009.6 |
| A130 | 130.0 |
| A1Z2EF3Y.9Z | 123.9 |
| A1239 | 239.0 |
| A50.5 | 050.5 |

The $B$ and $C$ commands each require 1 character following the command. The gain and reset values can be seen in Section 3.8 .

The $D$ code command is used to change from front panel controls to IEEE control or vice versa. The $D$ code acts as a flag toggle, in that, if the unit is under front panel control and the $D$ command is sent to the DRC instrument, then it will respond to changes only from the interface. If the $D$ command is sent again, the instrument returns to front panel control. Therefore, on odd times for the $D$ command being sent the unit is in remote control, and on even times the unit is in front panel control.

As an example, a controller sends the ASCII sequence,
A1 30.0B9C5D

| A | is the set point code |
| :--- | :--- |
| 130.0 | five characters to represent the set point $\left(130.0^{\circ} \mathrm{K}\right)$ |
| B | is the gain code |
| 9 | is the setting for resistors (1001) |
| C | is the reset code |
| 5 | is the setting for resistors ( 0101 ) |
| D | is the flag to convert controller operation |
|  | (if no other D has been sent through, this one |
|  | switches control from front panel to IEEE). |

The interface looks for one of two input terminators. The DRC8-IEEE will return to normal operation when the EOI command is accepted on input. The DRC8-IEEE will also look for an input delimiter depending on the position of switch 1 of the address switch. The following table shows the input delimiter selection.

Switch 1 Position
Input Delimiter
UP (OFF)
DOWN (ON)
(CR)
(LF)

The DC (Device Clear) command on the IEEE bus will clear the flag and return control of the set point to the front panel.

### 3.9.3 Sample Programming

This section contains some sample programming for the DRC8-IEEE option.

### 3.9.3.1 Commodore Pet/CBM 2001

Set the address switch to 6 by putting address switches 6 and 7 down; 8, 5 and 4 up. Make sure switches 2 and 3 are up (off) to allow the DRC8-IEEE to both talk and listen. Set switch 1 up (off) to select (LF) (CR) as the delimiter orientation. NOTE: The address switch is updated only on power up. Connect the CBM IEEE cable to the DRC8-IEEE interface. Turn on the PET and enter the program below, including line numbers, by pressing the return key after every line. After entering the program, type RUN and press the return key. The display will read "ENTER ". To set the set point to 130.0 , the remote gain value to 5 , the remote reset value to $A$, and toggle the flag to external control type in Al30B5CAD and press return. The display will then return those values just set in and return for a new input.


### 3.9.3.2 $\mathrm{HP}-85$

Set the address switch to 6 by putting address switches 6 and 7 down; 8, 5 and 4 up. Make sure switches 2 and 3 are up (off) to allow the DRC8-IEEE to both talk and listen. Set switch 1 down (on) to select (CR) (LF) as the delimiter orientation. NOTE: The address switch is updated only on power up. Connect the DRC8-IEEE to the IEEE interface of the HP-85. Turn on the unit and enter the program below, including line numbers, by pressing the END LINE key after every line. Press the RUN key. The display will read "ENTER ". To set the set point to 130.0 , the remote gain value to 5 , the remote reset value to $A$, and toggle the flag to external control, type in A130B5CAD and press the END LINE key. The display will then return those values just set in and return for a new input.

| 10 DISP"ENTER | "@INPUTA\$ |
| :--- | :---: |
| 20 OUTPUT706;AS |  |
| 30 ENTER706;G\$,R\$,P\$, | S\$, T\$ |
| 40 PRINT |  |
| 50 PRINT | $" ; G \$$ |
| 60 PRINT"GAIN | $" ; R \$$ |
| 70 PRINT"RESET | $" ; P \$$ |
| 80 PRINT"PANEL | $" ; S \$$ |
| 90 PRINT"SET POINT | $" ; T \$$ |
| 100 PRINT"TENPERATURE |  |
| 110 GOTO10 |  |
| HP-9845B |  |

Set the address switch to 6 by putting address switches 6 and 7 down; 8, 5 and 4 up. Make sure switches 2 and 3 are up (off) to allow the DRC8-IEEE to both talk and listen. Set switch 1 down (on) to select (CR) (LF) as the delimiter orientation. NOTE: The address switch is updated only on power up. Connect the DRC8-IEEE to the 98034A IEEE interface of the 9845B. Turn on the unit and enter the program below, including line numbers, by pressing the STORE key after each line is entered. Press the RUN key. The display will read "ENTER ". To set the set point to 130.0 , the remote gain value to 5 , the remote reset value to $A$ and toggle the flag to external control, type in Al30B5CAD and press the CONT key. The display will then return those values just set in and return for a new input.

| 10 DIMG\$[5], R\$[5], P\$[5],S\$[10],T\$[10], A\$[20] |  |  |
| :---: | :---: | :---: |
|  | INPUT"ENTER | ";A\$ |
| 30 OUTPUT706;A\$ |  |  |
|  | ENTER706;G\$,R\$, P\$, S\$,T\$ |  |
|  | PRINT |  |
|  | PRINT |  |
| 70 | PRINT"GAIN | ";G\$ |
|  | PRINT'RESET | ';R\$ |
| 90 | PRINT"PANEL | '; P\$ |
|  | PRINT"SETPOINT | ";S\$ |
| 110 | PRINT"TEMPERATURE | ";T\$ |
|  | GOTO20 |  |
|  | 9825A |  |

Set the address switch to 6 by putting address switches 6 and 7 down; 8, 5 and 4 up. Make sure switches 2 and 3 are up (off) to allow the DRC8-IEEE to both talk and listen. Set switch 1 down (on) to select (CR) (LF) as the delimiter orientation. NOTE: The address switch is updated only on power up. Connect the DRC8-IEEE to the 98034A IEEE interface of the 9825A. Turn on the unit and enter the program below by pressing the STORE key after each line is typed. Press the RUN key. The display will read
"ENTER ". To set the set point to 130.0 , the remote gain value to 5 , the remote reset value to A and toggle the flag to external control, type Al30B5CAD and press the CONT key. The printer will read the values just set in and return for a new input.

```
    O dimG$[5],R$[5],P$[5],S$[10],T$[10],A$[20].
    1 ent"ENTER ",A$
    2 wrt706,A$
    3 red706,G$,R$,P$,S$,T$
    4 prtG$
    5 prtR$
    6 ~ p r t P \$ ~
    prtS$
    8 \text { prtT\$}
    gtol
```

3.9.3.5 HP-9835A

Set the address switch to 6 by putting address switches 6 and 7 down; 8, 5 and 4 up. Make sure switches 2 and 3 are up (off) to allow the DRC8-IEEE to both talk and listen. Set switch 1 down (on) to select (CR) (LF) as the delimiter orientation. NOTE: The address switch is updated only on power up. Connect the DRC8-IEEE to the 98034A interface of the HP-35A. Turn on the unit and enter the program below by pressing the STORE key after each line is typed. Press the RUN key. The display will read "ENTER ". To set the set point to 130.0 , the remote gain value to 5 , the remote reset value to $A$ and toggle the flag to external control, type Al30B5CAD and press the CONT key. The display will read the values just set in and return for a new input.

| 10 | INPUT' ENTER | ";A\$ |
| :---: | :---: | :---: |
| 20 OUTPUT706;A\$ |  |  |
| 30 ENTER706;G\$,R\$,P\$,S\$,T\$ |  |  |
| 40 PRINT |  |  |
| 50 | PRINT |  |
| 60 | PRINT"GAIN | ";G\$ |
| 70 | PRINT"RESET | ";RS |
| 80 | PRINT"PANEL | ";P\$ |
| 90 | PRINT"SETPOINT | "; ${ }^{\text {S }}$ |
| 100 | PRINT"TEMPERATURE | ";T\$ |
| 110 | G0T010 |  |

3.10 Installation of DRC BCD/L-A Option Board

The installation of the DRC BCD/L-A option board can be done as follows:

1) Remove instrument cover.
2) Insert the BCD/L-A option board into instrument JE connector (the instrument has its edge card connector configured such that the option board can only be inserted in one way).
3) Take 50 pin ribbon connector, with mounting plate attached, and secure it in Interface opening, J4 (after any existing plate is removed). Place 14 pin header connector into board connector JF (noting Pin 1 to Pin 1 alignment).

Note: Ribbon cable and 14 pin header are only present for BCD option.
4) If set point is to be controlled externally, main circuit board jumpers JMP1 and JMP2 must be cut.
5) Connect black (or green) and white wires of BCD/L-A board to 7 pin rear panel connector J3. White goes to pin $C$ and black (or green) goes to pin $D$.
6) Replace instrument cover.
3.11 Installation of DRC IEEE Option Board

The installation of the DRC IEEE option board can be done as follows:

1) Remove instrument cover.
2) Remove blank plate covering $J 4$ connector on rear panel.
3) Install 14 pin header into connector JF. Install 24 pin header into JD'. Note pin 1 to pin 1 correlation. (See Figure 6.5 -DRC-84C Component Layout for connector locations).
4) Place option board in $J 4$ opening and secure in place with screws provided.
5) Replace instrument cover.
3.12 Rack Mounting the DRC-84C

The DRC-84C can be rack mounted with an $R M-3 F$ rack mounting kit. A typical full rack mount unit can be seen in Figure 3.4.


FIGURE 3.4 Typical Rack Mounted Unit


## SECTION IV

Theory of Operation

### 4.1 Introduction

The DRC-84C Thermometer/Controller is in actuality two instruments, a digital thermometer and an analog controller. A general description of the instrument is given in Section 4.2 with a detailed description in the following sections.
4.2 General Description

Refer to the DRC-84C Block Diagram (Figure 4.1) for the following discussion. Two precision 10 microampere constant current sources are used to excite the diode thermometers (Models DT-500-DRC, DT-500CU-DRC-36 or any $D T-500$ series sensor with a precision option). Front panel pushbuttons select which sensor is to be displayed and/or controlled.

Two precision 0.5 milliamperes constant current sources are used to excite the platinum resistance thermometers (Models PT-101, 102, and 103). Two ultra-stable amplifiers multiply the voltage signal by a factor of 20 so that 100 ohms is seen as a 1.0000 volt signal. Front panel pushbuttons select the type of sensor (diode or platinum) as well as which sensor is to be displayed and/or controlled.

The display sensor voltage is fed to an Analog-to-Digital converter pair (A/D), where it is converted to a digital voltage signal proportional to the sensor voltage. The multiplexed $B C D$ outputs from the $A / D$ are sampled and verified by the microprocessor. The microprocessor executes a program which takes the sampled sensor voltage and, using break point voltage and temperature information stored in a tabulator array, calculates the associated Kelvin temperature to better than 0.01 Kelvin. The microprocessor then outputs the temperature information to the display board. The decoder/driver decodes this temperature data, latches the information and drives the display digits.

The sensor display voltage is also available as a buffered output through the monitor plug on the rear of the instrument.

The control section of the instrument is essentially independent of the display or thermometer section. To control at a particular temperature, the thumbwheel switches on the front of the instrument are set for the desired temperature. This information is then input into the microprocessor, and, by using the same breakpoint-temperature information, a digital set point voltage is calculated. This voltage is output through data latches to a 16 bit $D / A$ converter where an analog voltage corresponding to the set point temperature is generated.

©COPYRIGHT 1981, Lake Shore Cryotronics, Inc

FIGURE 4.1 DRC-84C Block Diagram

The control sensor voltage is input buffered and fed to an error amplifier along with the opposite sign set point voltage. The error amplifier generates a signal proportional to the gain setting. With the addition of reset (integral), output power is controlled and applied to the system through a twenty-five watt heater.

The microprocessor also controls the $B C D$ and IEEE options. These options remotely control the set point, gain and reset as well as indicating the display temperature.

### 4.3 Detailed Description

A detailed description of the operation of the DRC instrument is outlined in the following sections. The Figures required for each section will be denoted in that section.
4.3.1 Power Supplies

Please refer to Figure 6.1 (Schematic \#1) for the following discussion. There are eight different power supplies incorporated in the DRC-series instruments. The main power transformer, TX1, has split primaries for 115 or 230 volt $A C$ operation. The slide switch, $S 2$, selects the proper line voltage.

The first secondary is output through leads 1 and 3. This secondary is rectified by CR1 and a floating 15 volt supply is obtained through C1, C6, and the positive 15 volt regulator U1. This supply is used to power the constant current sources for diodes in the case of the DRC-80C and both diodes and platinum sensors in the case of the DRC-84C.

The second secondary, through leads 2,4 , and 6 , is full wave bridge rectified by CR2-5. A +15 volt supply is generated by $C 2$, $C 7$ and a positive 15 volt regulator U2. The negative 15 volt supply is generated by C3, C8 and voltage regulator U3. Both these supplies are used in the $A / D$ and $D / A$ converters as well as the analog section. Regulators $U 6$ and U7 with capacitors C10, C47, C48, and C11 generate plus and minus 8 volts for the low voltage, low offset operational amplifiers used in the analog section.

The third secondary is through leads 8,10 , and 12 and is full wave rectified by CR6-7. The five volt supply that is used by the TTL IC's is formed by $\mathrm{C} 4, \mathrm{C} 9$, and a 5 volt positive voltage regulator U4. A 5 volt half wave supply for the LED display is provided by CR8, C5 and the 5 volt positive regulator $U 5$. The reason for splitting the 5 volt supplies is to avoid the LED display from loading down the main 5 volt supply.

The eighth supply is used in the output power section and will be covered there.

### 4.3.2 Precision Current Sources and Input Switching

Please refer to Figure 6.2 (Current Sources, Input Connections, Switching Schematic \#2) for the following discussion.

An explanation of the constant current sources will be limited to the Sensor A source of the silicon diode since the four current source circuits are exactly the same with the exception of resistor values between the platinum and diode sources to achieve the two different values of current.

A precision reference voltage is generated by an internal temperature stabilized precision voltage reference (U12). Resistors R11 and trimpot R12 vary this voltage to match the voltage generated by feedback resistor R13. Resistor R13 has been selected to generate 4.99 V (by an adjustment of the reference voltage to equal this feedback.voltage). Op amp U15 drives an FET (U16) to generate a current flow through Pins $A$ and $B$ of the sensor connector.

The voltages generated by the sensors are fed to front panel push button switches S7, S8 and S9. Selector switch S7 selects the type of sensor selected, platinum or silicon. S10 then routes the appropriate voltage and type information to switches S 8 and S 9 . Switch S9 selects which sensor, A or B, will be the display sensor. This switch takes the appropriate sensor voltage and feeds it to the $A / D$ converter as well as informing the microprocessor of its position. Switch S8 selects which switch is the control sensor. This switch takes the voltage and feeds it to an input buffer amplifier to be used as the control voltage. This switch also identifies its position to the microprocessor.

Switch $S 10$ identifies whether or not the scale expand is in use.

Switch 56 selects the power setting and will be explained in detail in the power amplifier section (Section 4.3.5).

Buffer Amplifier U19 gives a buffered output of the display sensor which is available at the monitor plug. This amplifier can have an offset voltage as high as 0.5 mV . This is adjusted to zero with trim potentiometer, R20.

### 4.3.3 A/D Converter and Microprocessor Hardware

Please refer to Figure 6.3 (DRC-84C Schematic \#3) for the following discussion.

The Analog-to-Digital converter consists of a precision $4 \frac{1}{2}$ digit IC pair (8052A/7103A, U31 and U32) that produces a multiplexed BCD output that is accurate to $\pm 1$ count over the entire 40,000 count range. The 7103A (U31) runs on a 50 K Hz clock cycle generated by U33. This clock frequency allows for one reading every . 8 seconds (since one clock pulse is required to make one count; 50,000 pulses per second would allow for
1.2 readings per second). The digital signal is output in a bit-parallel byte serial form. The $A / D$ converter output is multiplexed by $U 27$ and $U 28$ and input by the microprocessor.

In addition to the $A / D$ information, the microprocessor inputs the front panel control information, external switch position, set point and optional inputs (BCD or IEEE), and outputs display information and set point voltage.

The microprocessor unit (MPU) used in the DRC-84C is a 38 P 70 which utilizes a piggy-back memory architecture. A $3870 \mu \mathrm{p}$ was originally a maskonly part with the user tied to one program form when the part was fabricated. The piggy-back variation of the part allows for variable memory space (between 8 K and 64 K of PROM ) to be placed on top of the $\mu \mathrm{p}$. This allows all lines that were used for addresses and data to be used for input/output.

The microprocessor unit has an internal RAM scratchpad memory used for programming. The unit derives its internal clock from resistor R23 (and C18, if needed). The MPU has four (4) 8-bit bi-directional ports used for communication to and from the processor. Two of these ports, Ports 0 and 5, are used for internal control of the instrument (A/D input, $B C D$ temperature output, set point voltage output, etc.). The remaining two ports, Ports 1 and 4, are used for option access (IEEE-488).

The CPU uses one of its $I / O$ ports to control Tri-State 8 -line to $4-1$ ine multiplexers (74LS257) controlled by a decoder/demultiplexer (74139) to input the information needed. The second of the 2 ports handles the input of data and manipulation of display data.

The CPU outputs the set point information through one of its $I / O$ ports as well.

The DRC-84C software is discussed in detail in Section 4.3.4.

### 4.3.4 Software

Refer to Figure 4.2 as an aid in the following discussion. The flow chart gives the major steps of the program. When the instrument is turned on, the program does a power on reset and starts the program at the beginning. At this point, the program initializes internal registers to be used in the program. The program first checks for an $A / D$ converter overrange and then inputs multiplexed $A / D$ information when the $A / D$ tells it there is fresh data ready (the program loops until the $A / D$ information is ready). The program then verifies that there are no illegal characters that were input and stores the reading. After the first cycle, a calculation is done with each $A / D$ reading.

The program then inputs display sensor information. There is one standard curve for the instrument and there are a maximum of twelve additional
curves for each type of sensor. There can be a calibrated curve for Sensor $A, B$ and ten different switch positions generated by the SW-10A. The program determines the type of sensor input and what curve to use for that sensor.

Once the curve is determined, the proper Voltage-Temperature Break Point is determined. The program finds the correct break point for temperature determination by checking each break point voltage to see if it is lower than the input voltage. As the break point is found, the temperature is calculated using the following equation:

$$
T=\left(V_{B P}-V_{A D}\right) * \frac{d T}{d V}+T_{B P}
$$

where:

| $T$ | is temperature in $K$ |
| :--- | :--- |
| $V_{B P}$ | is break point voltage |
| $V_{A D}$ | is input voltage |
| $\frac{d T}{d V}$ | is slope between successive break points |
| $T_{B P} \quad$ is break point temperature |  |

After the correct temperature has been calculated, the program looks to see if the instrument is in the scale expand mode. In this mode, the front panel display converts to a resolution of .01 K from. 1 K when below $100^{\circ} \mathrm{K}$.

If there is no LO 1 error condition (in the case of the platinum sensor) the temperature is output in a bit-parallel, digit-serial form and is latched into the display board.

Once the temperature has been output, the program looks to the set point. The program determines if there is an option present and if there will be a set point input from that option. If no option is present, the program reads the front panel thumbwheel switches. If an option is present, the front panel switches are ignored and the set point is read from the remote source.

The program then determines whether the LO 2, HI 1, or HI 2 errors have occurred. If so, the program continues and outputs the appropriate error to the display and loops back to input another set point until the error is corrected. The program then calculates the break point voltage in much the same way it calculates the temperature. The program determines which is the control sensor and its appropriate curve. It then calculates the set point voltage using the following equation:

$$
V_{S P}=\left(T_{B P}-T_{S P}\right) * \frac{d V}{d T}+V_{B P}
$$


where:

| $V_{S P}$ | is set point voltage in volts |
| :--- | :--- |
| $T_{B P}$ | is break point temperature |
| $T_{S P}$ | is set point temperature |
| $\frac{d V}{d T}$ | is slope between successive break points |
| $V_{B P}$ | is break point voltage |

At this point, the program converts the $B C D$ voltage to hexadecimal (base 16) and outputs it to the $D / A$ converter in complementary form.

The program then loops back to begin the cycle over again.

### 4.3.5 Analog Control and Set Point

Refer to Figure 6.4 (Schematic \#4) for the following discussion. The digital set point voltage information is output in digit serial, bit parallel form. The data is then latched by four quad latches, U34 through U37, using a data valid signal from U24. The data latched into the quad latches is in a complementary hexadecimal form. This data is converted by a D/A converter for a negative analog voltage (silicon) or positive (platinum) set point. The set point is then compared to the opposite polarity sensor voltage by amplifier $U 40$ and its associated circuitry. If the two signals are not equal in magnitude, this error signal is amplified with the amplification controlled by the gain control potentiometer on the front panel.

In order to understand the analog control circuitry, three different cases should be discussed (The examples will be covered for the diode. The examples can be applied to the platinum sensor, keeping in mind the platinum sensor has the opposite temperature coefficient of the diode.). It should be remembered that, in the case of the diode sensor, voltage decreases with increasing temperature, i.e., the diode is a negative temperature coefficient sensor.

For the first case, assume that the sample temperature is less than the decimal set point temperature. Therefore, the sensor voltage is greater than the set point voltage and the error signal is positive resulting in the inverting gain amplifier output being negative. Since the output amplifier is also an inverting amplifier, power is applied to the load. The amount of power is dependent on the magnitude of the error signal, the gain setting and also the magnitude of the integral signal.

If the combination of the gain and error signal are such that the output of the gain amplifier is more negative than two volts, the output amplification will result in full power being delivered to the load. For
this condition, an integral time is not required and is eliminated by using the comparator U42. The output gain is inverted resulting in a positive signal. If this signal is greater than two volts, the output of the comparator approaches the negative supply voltage and CR11 is forward biased. This in turn causes CR13 to become forward biased so that the integator is effectively removed from the circuit. However, when the output of the gain amplifier is between zero and a minus two volts, the comparator output approaches the positive supply voltage resulting in CR11 being shut off and R59 and R60 having no effect since pin 2 of amplifier $U 43$ is a virtual ground. The integrator will then integrate with a time constant which is proportional to the setting of the potentiometer R62 and the magnitude of the amplifier error signal. The output of the gain amplifier is summed with the output of the integrator to drive the heater circuit. When the error signal goes to zero, the integrator supplies a constant signal which keeps the output power constant and, therefore, the temperature constant.

For positive error signals, i.e., the sensor temperature greater than the set point temperature, the output power is kept on by the charge stored on the integrator. If the error signal stays positive, this charge drops off the integrator which gradually reduces the output power towards zero. The output of the integrator would go positive towards the supply voltage except that the diode CR13 shorts this output at about +0.4 volts.

The available power to the heater is generated by a power supply that consists of transformer TX2, full wave bridge rectifier (CR15-18) and a capacitor (C45). This transformer has its input voltage (115-230) selected by 52 . A split secondary is used for $\mathrm{HI} / \mathrm{LO}$ power selection. The low end of the secondary (Pin 1 of JN) is carried on to the diode full wave bridge. One of the other two points of the secondary is selected by $S 6$, the $H I / L O$ power selector on the front panel. This switch either picks a portion of the secondary voltage (LO power mode) or the entire secondary (HI power mode). The voltage selected is then rectified by the diode bridge and filtered by its capacitor and the power transistor and load. This voltage is applied to power transistor $U 45$. The amount of voltage applied to the load (J5 to J6) is then dependent on its loop gain of the controller, the voltage stored on the integrator and the magnitude of the error signal.

### 4.3.6 Digital Display Board

Please refer to Figure 6.6 (Display Board Schematic) and Figure 6.7 (Display Board Component Layout) as an aid in the following discussion.

The display board receives its data in a bit-parallel/digit-serial form. The information is latched into the display decoder/driver U101 which drives the display digits DS1-4.

Control of the decimal point is carried out by the BCD/decimal decoder/driver, U102. This driver receives its information directly from the microprocessor. Front panel pushbutton information is displayed by pilot light LED's, DS5-12, and are explained by information contained on the display glass.

This Page Intentionally Left Blank

SECTION V
Calibration and Troubleshooting

### 5.1 Introduction

This section contains the instructions for calibrating and troubleshooting the DRC-84C instrument.

### 5.1 Test Equipment

A high input impedance digital voltmeter and oscilloscope, a 25 ohm, 25 watt resistor to simulate a heater element, and a precision resistor connected to simulate the diode wired according to Figure 2.1 (c) are normally sufficient to test and calibrate the DRC-84C instrument.

### 5.3 General Remarks

On installation, one of the major problems is an improperly connected temperature sensing diode. It is advised that other portions of the cryogenic system be tested before the instrument is troubleshooted. Some checks that could be made are:

1) Open or shorted sensor or heater leads (especially in an area of frequent disassembly).
2) Leakage paths between heater and sensor leads that induce electrical feedback in addition to thermal feedback.

If the malfunction points toward the instrument, more detailed tests should be made.

### 5.4 Instrument Calibration

The $D R C-84 C$ has been factory calibrated. If a recalibration is needed, the following procedure should be followed. Please refer to the component layout for the DRC-84C, Figure 6.5 for the following discussion:

### 5.4.1 Current Sources

a) Current Source - Diode Sensor A

A precision resistor of not less than . $01 \%$ tolerance should be connected across pins $A$ and $B$ (Figure 2.1) of the diode A Sensor socket. A high input impedance voltmeter connected across the precision resistor should measure a voltage equal to 10 micro amperes times the value of the resistor. For example, a 100 K ohm $\pm .01 \%$ resistor should read 1.0000 volts within $100 \mu$ volts. If recalibration is needed, the voltage across the 100 K resistor can be adjusted by varying resistor $R 12$.
b) Current Source - Diode Serisor B

The above procedure can be followed with the diode B Sensor socket. R9 should be varied for this adjustment.
c) Current Source - Platinum Sensor A

A 100 ohm precision resistor of not less than $0.1 \%$ tolerance should be connected across pins $A$ and $B$ (Figure 2.1) of the platinum A Sensor socket. A high input impedance voltmeter connected across the precision resistor should measure a voltage equal to 0.5 milli-amperes times the value of the resistor. For example, a 100 ohm $\pm 0.1 \%$ resistor should read 50 millivolts within 5 uvolts. If recalibration is needed, the voltage across the 100 ohm resistor can be adjusted by varying resistor $R 3$.
d) Current Source - Platinum Sensor B

The above procedure can be followed with the platinum B Sensor socket. R5 should be varied for this adjustment.

### 5.4.2 A/D Converter

To adjust the $A / D$ converter, a voltage needs to be applied across pins E and D (Figure 2.1) of the display sensor connector for the diode-A. A variable 200 K resistor hooked up as in Fig. 2.1 (a), or precision voltage source in place of the diode are ideal ways to generate this voltage. If a resistor is used, it should be varied until one of the breakpoint voltages, indicated in the Voltage-Temperature Characteristic Table is generated (A high impedance voltmeter must be used for this adjustment). After an appropriate voltage is obtained, the display should be calibrated by adjusting trimpot R 38 until the display reads the correct temperature. If a precision voltage source is used, a breakpoint voltage should be dialed in and the display should be calibrated as above. A breakpoint temperature above 40 K should be used since the voltage sensitivity with temperature is lower at the higher temperatures ( $2.5 \mathrm{mV} /{ }^{\circ} \mathrm{K}$ ) than for temperatures below 30 K .
5.4.3 D/A Converter
a) D/A Verify

Pins 1 through 16 of U 38 have parallel data present representing the set point voltage generated by the set point switches. The data is in complimentary hexadecimal form. As an example, a decimal-hex table is given in Table 5.l:

Table 5.1

| Decimal | Hexadecimal | Complimentary Hexadecimal |
| :---: | :---: | :---: |
| 0 | 0 | F |
| 1 | 1 | E |
| 2 | 2 | D |
| 3 | 3 | C |
| 4 | 4 | B |
| 5 | 5 | A |
| 6 | 6 | 9 |
| 7 | 7 | 8 |
| 8 | 8 | 7 |
| 9 | 9 | 6 |
| 10 | A | 5 |
| 11 | B | 4 |
| 12 | c | 3 |
| 13 | D | 2 |
| 14 | E | 1 |
| 15 | F | 0 |

The following table (Table 5.2) gives a set of data for pins 1-16 for the two standard curves $D$ and $E$ as well as for the $D / N$ standard curve for the platinum input.

Table 5.2
Curve D
T (Set Point) Data (Pin 1-4, 5-8, 9-12, 13-16)

| 004.0 | 1011 | 1111 | 0010 | 0100 |
| :--- | :--- | :--- | :--- | :--- |
| 022.0 | 1010 | 0001 | 0100 | 1001 |
| 130.0 | 1001 | 0101 | 1010 | 1000 |
| 300.0 | 1000 | 1001 | 1010 | 1100 |

Curve E
T (Set Point) Data

| 004.0 | 1100 | 0000 | 1110 | 1100 |
| :--- | :--- | :--- | :--- | :--- |
| 022.0 | 1010 | 0010 | 0011 | 0010 |
| 130.0 | 1001 | 0101 | 1010 | 0000 |
| 300.0 | 1000 | 1001 | 1010 | 0000 |


| T(Set Point) | Data (Pin 1-4, | $5-8,9-12,13-16)$ |  |  |
| :--- | :---: | :---: | :---: | :---: |
| 077.0 | 0111 | 1010 | 1101 | 1100 |
| 130.0 | 0111 | 0101 | 0001 | 1111 |
| 300.0 | 0110 | 0011 | 1011 | 1011 |

The previous sets of data were given for the purpose of data verification. If the data does not match, refer to Section 6.5 to find the problem.
b) D/A Calibrate

The calibratioin of the $D / A$ converter is an iterative process using a span and offset potentiometer to get a calibrated reading.

The reading can be calibrated in one of two methods:
(1) Method 1 - Use of the Voltmeter

With the voltmeter connected between ground and TP非1, a negative voltage (for diodes) should be present that corresponds to the set point temperature from the front panel thumbwheel switches. As an example, Curve D is used to calibrate the instrument for a $D$-curve sensor; the curve the instrument has can be noted from the sticker on PROM U20. The curve is denoted in parenthesis (*).

A temperature is dialed in to give a fairly low voltage reading, for example 330.0 K . The voltage read on the voltmeter should be -. 29111 V . Trimpot R 41 is varied until this reading is obtained. Then a temperature point is selected to give a higher voltage reading, for example, 21.0 K . The voltage read on the voltmeter should be -1.3505 V . Trimpot R 42 is varied until this reading is obtained. This process should be repeated until no further trim adjustments are needed.
(2) Method 2 - Use of Display

The DRC-84C incorporates a method by which the D/A converter can be tied to the input sensor voltage line. With no sensor in either rear panel connector, TP1 and TP2 should be tied together. This links the D/A output with the $A / D$ converter input.

The same iterative process should be used as in Method (1) with the exception that the display should read the setpoint setting.

Note: This method should be used in the diode type only. The linearity of the converter is the same for diodes and platinum. If this method is used for the platinum type, the high stability instrumentation amplifiers of the platinum input may be damaged.

Note: An $A / D$ that is in calibration is vital to the accuracy of this method of calibration.

### 5.4.4 Output Buffer

With a constant voltage fed into the instrument, as in the $A / D$ converter calibration, place the voltmeter between Pins A and B of 7 pin rear panel connector J3. This voltage should be equal to the input voltage. R20 is varied to obtain the proper buffered signal.

### 5.4.5 DRC L/A Option (if present)

The output of the DRC L/A option outputs $10 \mathrm{mV} / \mathrm{K}$ relative to display temperature. In other words, $100.0{ }^{\circ} \mathrm{K}$ on the display corresponds to a 1.0000 V output between Pins C and D of monitor connector J3. To recalibrate the option, two adjustments need to be made. With a low temperature on the display (e.g., $22.0^{\circ} \mathrm{K}$ ), adjust the offset adjustment potentiometer R89 (see Figure 6.9 - DRC-80C BCD/L-A Option Component Layout) until the output corresponds to $10 \mathrm{mV} / \mathrm{K}$. Then take the display to a higher temperature (e.g., $300^{\circ} \mathrm{K}$ ). Adjustment of gain potentiometer 888 will bring the output to $10 \mathrm{mV} / \mathrm{K}$. The procedure may need one more iteration, that is, go to the low temperature on the display, adjust the offset, then go to high temperature display and adjust the gain again.

### 5.5 Instrument Tests

The first check to be made would be to check the input line fuse. The type of fuse and line voltage are shown on the rear panel of the instrumert. If the input line voltage and sensor input voltage have been checked, the following sequence should be followed:

1) Check all the power supplies for proper operation. Power supply lines are indicated in Figure 6.5 (Component Layout).
2) Check for the waveforms at the following pins and refer to Table 5.3 for waveforms.

Table 5.3
DRC-84C Signals

| Signal | Function | Wave Form |
| :---: | :---: | :---: |
| a) Pin 12 of U31 or Pin 3 of U32 | Clock signal of $A / D$ converter. The frequency should be about 50 K Hz . If not present, replace U32. Also check R34, R35 and C26. |  |
| b) Pin 14 of U32 | Integrated signal of $A / D$ to determine the count period. The period should be about . 35 seconds. If not present, check U31 and U32. |  |
| c) Pin 7 of U31 | This is a D.C. level that is the reference voltage for the integrator. The value should be between 1.4 and 1.8 volts. If not present, check U32. Also check resistance string R36-39 for proper value and operation. |  |
| d) $A / D$ Output of U31 | The digit drives (Pins 19, 24, 25, 26 , and 27) are positive going pulses and last for 200 clock pulses. The scan sequence is D5 (MSD), D4, D3, D2, and D1 (LSD). The BCD pins (pins 20-23) are positive going signals that go on simultaneously with the digit device. If not present, and signals a), b), and c) are correct, replace U31. |  |
| e) Pin 2 of U 40 | This is the $\mu \mathrm{P}$ clock signal. This is generated by an external RC network with the help of the main processor. If not present, check R23, C18, and U20 for proper operation. |  |

Signals from this point on are of a D.C. nature. A general explanation of the D.C. levels is given in the following Table 5.4:

Table 5.4

| Signal | Function |
| :--- | :--- |
| 1) Input buffer U39 | This op-amp circuit is used to buffer <br> the incoming control sensor voltage <br> so that there will be no current load <br> on the sensor. Resistor R33 varies <br> the output. If the voltage at pin 6 <br> cannot be varied until it equals pin <br> 3, U44 may be bad. |
| 2) Summing amplifier U40 | This unit uses current summing to <br> obtain an error signal. With the <br> voltages TP\#1 and TP\#5 equal and <br> opposite, the output of U40 should <br> be nulled (approx. <br> is not present, U40 may be bad. this |
| 3) Integrating amplifier | If, with an error signal, the inte- <br> grator does not integrate (increase |
| output voltage at TP\#4 with time), |  |
| check U41, U42, and U43. |  |

Signal paths should also be checked. If signals are present at source comporents and not at destination components, a printed circuit problem requiring a repair of the printed circuit foil may be required. Continuity checks between points will turn up any unwarited open circuits in signal paths.

If the signals at the component pins outlined in Table 5.3 and 5.4 are present, and a problem still exists, a factory representative should be contacted.

This Page Intentionally Left Blank

DRC-84C
REPLACEABLE PARTS LIST
6.1 Main Board Components

CAPACITORS

| CIRCUIT |  |  |  |
| :---: | :---: | :---: | :---: |
| DESIGNATION | VALUE | RATING | TYPE |
| C1 | 470 Hf | 35 V | E. Al. |
| C 2 | 470 ¢f | 35 V | E. Al. |
| C3 | $470 \mu \mathrm{f}$ | 35 V | E. Al. |
| C4 | $2700 \mu \mathrm{f}$ | 25 V | E. Al. |
| C5 | $470 \mu \mathrm{f}$ | 35 V | E. Al. |
| C6 | . $1 \mu \mathrm{f}$ | 100 V | Poly. |
| C7 | . $1 \mu \mathrm{f}$ | 100 V | Poly. |
| C8 | . $1 \mu \mathrm{f}$ | 100 V | Poly. |
| C9 | . $1 \mu \mathrm{f}$ | 100V | Poly. |
| C10 | . $1 \mu \mathrm{f}$ | 100 V | Poly. |
| C11 | . $68 \mu \mathrm{f}$ | 100 V | Poly. |
| C12 | . $0015 \mu \mathrm{f}$ | 100 V | Mylar |
| C13 | 150 pf | 500 V | Mica D. |
| C14 | . 0015 ¢f | 100 V | Mylar |
| C15 | 150 pf | 500 V | Mica D. |
| C16 | . $0015 \mu \mathrm{f}$ | 100 V | Mylar |
| C17 | 150 pf | 500 V | Mica D. |
| C18 | Not used |  |  |
| C19 | . $68 \mu \mathrm{f}$ | 100V | Poly. |
| C20 | . $33 \mu \mathrm{f}$ | 100 V | Mylar |
| C21 | . $68 \mu \mathrm{f}$ | 100 V | Poly. |
| C22 | . $68 \mu \mathrm{f}$ | 100 V | Poly. |
| C23 | . $68 \mu \mathrm{f}$ | 100 V | Mylar |
| C24 | . $68 \mu \mathrm{f}$ | 100 V | Poly. |
| C25 | . $33 \mu \mathrm{f}$ | 100 V | Mylar |
| C26 | 330 pf | 500 V | Mica D. |
| C 27 | 330 pf | 500 V | Mica D. |
| C28 | $1.5 \mu \mathrm{f}$ | 25 V | Tan. |
| C29 | . $1 \mu \mathrm{f}$ | 100 V | Poly. |
| C29A | $.68 \mu \mathrm{f}$ | 100 V | Poly. |
| C30 | . $68 \mu \mathrm{f}$ | 100 V | Poly. |
| C31 | $.68 \mu \mathrm{f}$ | 100 V | Poly. |
| C32 | . $033 \mu \mathrm{f}$ | 100 V | Mylar |
| C33 | . 033 นf | 100 V | Mylar |
| C34 | . $033 \mu \mathrm{f}$ | 100 V | Mylar |
| C35 | . $033 \mu \mathrm{f}$ | 100 V | Mylar |
| C36 | . $033 \mu \mathrm{f}$ | 100 V | Mylar |
| C37 | Not used |  |  |
| C38 | . $033 \mu \mathrm{f}$ | 100 V | Mylar |
| C39 | . $033 \mu \mathrm{f}$ | 100 V | Mylar |
| C40 | . $033 \mu \mathrm{f}$ | 100 V | Mylar |

CAPACITORS

| CIRCUIT |  |  |  |
| :---: | :---: | :---: | :---: |
| DESIGNATION | VALUE | RATING | TYPE |
| C41 | . $033 \mu \mathrm{f}$ | 100V | Mylar |
| C42 | . $033 \mu \mathrm{f}$ | 10 V | Mylar |
| C43 | . $033 \mu \mathrm{f}$ | 100 V | Mylar |
| C44 | . $68 \mu \mathrm{f}$ | 100 V | Mylar |
| C45 | 2400 ¢f | 50 V | E. Al. |
| C46 | . $68 \mu \mathrm{f}$ | 100 V | Poly. |
| C47 | . $68 \mu \mathrm{f}$ | 100 V | Poly. |
| C48 | . $68 \mu \mathrm{f}$ | 100 V | Poly. |
|  | CONNEC |  |  |
| CIRCUIT |  |  |  |
| DESIG. | DESCRIPTION |  | MFR. and PART NO. |
| J 1 | 5 Pin Socket (Sensor A) |  | Amphenol 126-218 <br> (mates with 126-217) |
| J 2 | 5 Pin Socket (Sensor B) |  | Amphenol 126-218 (mates with 126-217) |
| J3 | 7 Pin Socket (Monitor) |  | Amphenol 126-193 (mates with 126-195) |
| J4 | BCD/IEEE In-Out (Interface) |  | Lake Shore Cryotronics, Inc. |
| J 5 | Grey Binding Post (Heater V+ Out) |  | E.F. Johnson $111-0113-001$ |
| J6 | Black Binding Post <br> (Heater $\mathrm{V}_{-}$Out) |  | E.F. Johnson $111-0103-001$ |
| J 7 | Black B <br> (Heater | Post | E.F. Johnson 111-0103-001 |
| JA | 10 Contact PC Mount (Display Board) |  | AMP MODII 3-86018-5 (mates to JG) |
| JB | 10 Contact PC Mount (Display Board) |  | AMP MODII 3-86018-5 (mates to JH) |
| JC | 16 Pin IC Socket (SW-10 Input of switch position) |  | $\begin{aligned} & \text { Cambion } \\ & 703-5316-01-04-12 \end{aligned}$ |
| JD' | 24 Pin IC Socket <br> (IEEE Interface Connection) |  | $\begin{aligned} & \text { Cambion } \\ & 703-5324-01-04-12 \end{aligned}$ |
| JE | 24 Contact Edge Card (BCD/L-A Option) |  | TRW 50-24B-10 |
| JF | 14 Pin IC Socket (Gain-Reset Option Input) |  | $\begin{aligned} & \text { Cambion } \\ & 703-5314-01-04-12 \end{aligned}$ |
| JG | 10 Contact PC Mount (To Display Board) |  | AMP 87228-5 <br> (mates to JA) |


| JH | 10 Contact PC Mount (To Display Board) | $\begin{aligned} & \text { AMP 87228-5 } \\ & \text { (mate to JB) } \end{aligned}$ |
| :---: | :---: | :---: |
| JL | 16 Contact PC Mount (Power Transformer) | AMP 350214-1 <br> (mates to $\begin{aligned} 1-480 \\ 438-0)\end{aligned}$ |
| JM | 3 Contact Transistor (Mounts on U45)) | Molex-10-17-2032 |
| JN | 8 Contact PC Mount (Heater Output Transformer) | $\begin{aligned} & \text { AMP } 350212-1 \\ & \text { (mates to } 1-480 \\ & 285-0 \text { ) } \end{aligned}$ |

DIODES

## CIRCUIT

DESIG.
TYPE MFR. and PART NO.
CR1
CR2
CR3
CR4
CR 5
CR6
CR 7
CR8
CR9
CR10
CR11
CR12
CR13
CR14
CR15
CR16
CR17
CR18
DS1
DS 2
DS 3
DS4
DS 5

| Silicon | IN4006 |
| :--- | :--- |
| Silicon | IN4006 |
| Silicon | IN4006 |
| Silicon | IN4006 |
| Silicon | IN4006 |
| Silicon | MR501 |
| Silicon | MR501 |
| Silicon | MR501 |
| Silicon | IN743 |
| Silicon | IN743 |
| Not Used |  |
| Silicon | IN4148 |
| Silicon | IN459 |
| Silicon | IN459 |
| Silicon | MR501 |
| Silicon | MR501 |
| Silicon | MR501 |
| Silicon | MR501 |

7 Segment LED Hewlett-Packard 5082-7651
(Least Significant Digit)
7 Segment LED Hewlett-Packard 5082-7651
(2nd Significant Digit)
7 Segment LED Hewlett-Packard 5082-7651
(3rd Significant Digit)
7 Segment LED Hewlett-Packard 5082-7651
(Most Significant Digit)
Pilot Light LED
Hewlett-Packard 5082-4494
(Scale Expand Indicator)

| CIRCUIT |  |  |  |
| :---: | :---: | :---: | :---: |
| DESIG. | TYPE | MFR. and PART NO |  |
| DS6 | Pilot Light LED <br> (Scale Normal Indicator) | Hewlett-Packard | 5082-4494 |
| DS 7 | Pilot Light LED <br> (B Display Indicator) | Hewlett-Packard | 5082-4494 |
| DS8 | Pilot Light LED <br> (A Display Indicator) | Hewlett-Packard | 5082-4494 |
| DS9 | Pilot Light Indicator <br> (B Control Indicator) | Hewlett-Packard | 5082-4494 |
| DS10 | Pilot Light Indicator <br> (A Control Indicator) | Hewlett-Packard | 5082-4494 |
| DS11 | Pilot Light Indicator (Hi Power Indicator) | Hewlett-Packard | 5082-4494 |
| DS12 | Pilot Light Indicator (Low Power Indicator) | Hewlett-Packard | 5082-4494 |
| DS13 | Pilot Light Indicator | Hewlett-Packard | 8052-7656 |
| DS14 | Pilot Light Indicator | Hewlett-Packard | 5082-4494 |
| DS15 | Pilot Light Indicator | Hewlett-Packard | 8052-4494 |

GIRCUIT DESIG.

DESCRIPTION PART NO.
U1
U2
U3
U4
U5
U6
U7
U8
U9
U10
U11
U12

U13
U14

| CIRCUIT |  |  |
| :---: | :---: | :---: |
| DESIG. | DESCRIPTION | PART NO. |
| U15 | Operational Amplifier (Current A) | LM308N |
| U16 | $\begin{aligned} & \text { F.E.T. } \\ & \text { (Sensor A Current Driver) } \end{aligned}$ | 3N163 |
| U17 | Operational Amplifier | AD 522 |
| U18 | Operational Amplifier | AD 522 |
| U19 | Operational Amplifier (Output Buffer) | OP07EJ |
| U20 | Microprocessor Unit (with piggy-back PROM) | $\begin{aligned} & 38 \mathrm{P} 70 \\ & \text { Plus PROM } \\ & (2716 \text { or } 2532) \end{aligned}$ |
| U21 | Decoder/Multiplexer | 74 LS 139 |
| U22 | Decoder/Multiplexer | 74LS 139 |
| U23 | Hex Inverters | 7404 |
| U24 | Hex Inverters | 7404 |
| U25 | Tri-State Quad 2-data Selectors/Multiplexers | 74LS 257 |
| U26 | Tri-State Quad 2-data Selectors/Multiplexers | 74LS 257 |
| U27 | Tri-State Quad 2-data Selectors/Multiplexers | 74LS 257 |
| U28 | Tri-State Quad 2-data Selectors/Multiplexers | 74 LS 257 |
| U29 | Tri-State Quad 2-data Selectors/Multiplexers | 74LS 257 |
| U30 | Decoder/Multiplexer | 74LS 139 |
| U31 | A/D Converter Building Block | 7103A |
| U32 | A/D Converter Building Block | 8052A |
| U33 | Timer Circuit | NE 555N |
| U34 | Quad Latch | 4042 |
| U35 | Quad Latch | 4042 |
| U36 | Quad Latch | 4042 |
| U37 | Quad Latch | 4042 |
| U38 | 16-Bit D/A Converter | HP16-BGC |
| U39 | Operational Amplifier (Input Buffer) | ICL-7650 |
| U40 | Operational Amplifier (Summing Amplifier) | ICL-7650 |
| U41 | Operational Amplifier | ICL-7650 |
| U42 | Operational Amplifier | ICL-7650 |
| U43 | Operational Amplifier <br> (Integrating Amplifier) | ICL-7650 |
| U44 | Operational Amplifier (Output Driver) | MC1436CU |
| U45 | 8-Ampere Darlington Power Transistor | 2N6044 |

MISCELLANEOUS

| $\begin{aligned} & \text { CIRCUIT DESIG. } \\ & \text { or FIG. NO. } \end{aligned}$ | DESCRIPTION | MFR. \& PART NO. |
| :---: | :---: | :---: |
| F1 | Main Fuse 3 AG, Slow Blow 90V-125V:3/4A 210V-250V:4/10A Fuseholder | ```Bussmann MDL 3/4 Bussmann MDL 4/10 Littlefuse 342004A``` |
| F2 | Heater Fuse 3AG, Slow Blow 1A Fuseholder | Bussmann MDL 1 Littlefuse 342004A |
| TX1 | Power Transformer | LSCI supplied TX 696-107 |
| TX2 | Heater Transformer | TX 696-106 <br> LSCI supplied |
|  | Power Cord: 115 V : | Belden 17236 |
|  | CEE Color Coded:230V | Belden 17740C |
|  | Strain Relief | $\text { H.H. Smith } 939$ |
|  | Heat Sink for U4 | Aavid 5772B |
|  | RESISTORS |  |
| CIRCUIT |  |  |
| DESIG. | VALUE RATING | TYPE |
| R1 | 3.74 K | Mt.F. |
| R2 | 20K 1\% $\frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R3 | 5K Trimpot | nes 3059Y-1-502 |
| R4 | 2 K | Mt. F. |
| R5 | 5K Trimpot | nes 3059Y-1-502 |
| R6 | 12 K | Mt. F. |
| R7 | 12 K | Mt. F. |
| R8 | 10K 1\% $\frac{1}{4}$ | Mt. F. |
| R9 | 5K Trimpot Sensor | Source Adjust) <br> rnes 30594-1-502 |
| R10 | 499K $1 \%$ 考 W | Mt.F. |
| R11 | 10K $1 \% \frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R12 | 5K Trimpot (Sensor | Source Adjust) rnes 30594-1-502 |
| R13 | 499 K | Mt. F . |



RESISTORS

6.2 DRC-84C BCD-L/A arıd IEEE Components List

CAPACITORS

| CIRCUIT |  |  |  |
| :---: | :---: | :---: | :---: |
| DESIGNATION | VALUE | RATING | TYPE |
| C56 | . $033 \mu \mathrm{f}$ | 100V | Mylar |
| C57 | . $68 \mu \mathrm{f}$ | 100 V | Poly. |
| C58 | . $68 \mu \mathrm{f}$ | 100 V | Poly. |
| C59 | . $68 \mu \mathrm{f}$ | 100 V | Poly. |
| C200 | $.1 \mu \mathrm{f}$ | 100 V | Poly. |
| C201 | $.1 \mu \mathrm{f}$ | 100 V | Poly. |
| C202 | $.1 \mu \mathrm{f}$ | 100 V | Poly. |
| C203 | $.1 \mu \mathrm{f}$ | 100 V | Poly. |
| C204 | $.1 \mu \mathrm{f}$ | 100 V | Poly. |
| C205 | $.1 \mu \mathrm{f}$ | 100 V | Poly. |
| C206 | $.1 \mu \mathrm{f}$ | 100 V | Poly. |
| C 207 | $.1 \mu \mathrm{f}$ | 100 V | Poly. |
| C208 | $18 \mu \mathrm{f}$ | 500 V | Mica. D. |
| C210 | $.1 \mu \mathrm{f}$ | 100 V | Poly. |
| C211 | $.1 \mu \mathrm{f}$ | 100 V | Poly. |

CONNECTORS

CIRCUIT

| DESIGNATION | DESCRIPTION | MFR. and PART NO. |
| :---: | :---: | :---: |
| J4 (BCD option) | 50 pin Connector | T\&B Ansley 609-5016 (Mates with T\&B Ansley 609-5030) |
| J4 (IEEE option) | 24 pin Connector | AMP 552791-1 <br> (Mates with IEEE cable connector) |
| ```JD (IEEE option - S/N 4136 or lower)``` | 16 pin IC Socket (IEEE Interface Connection) | $\begin{aligned} & \text { Cambion } \\ & 703-5316-01-04-12 \end{aligned}$ |
| ```JD' (IEEE option - S/N 4137 or higher)``` | 24 pin IC Socket (IEEE Interface Connection) | $\begin{aligned} & \text { Cambion } \\ & 703-5324-01-04-12 \end{aligned}$ |
| JF | 14 pin IC Socket <br> (Gain-Reset Control) | $\begin{aligned} & \text { Cambion } \\ & 703-5314-01-04-12 \end{aligned}$ |

DESCRIPTION

50 pin Connector

24 pin Connector AMP 552791-1
(Mates with IEEE cable connector)
16 pin IC Socket Cambion
(IEEE Interface 703-5316-01-04-12
Connection)
24 pin IC Socket Cambion
(IEEE Interface
14 pin IC Socket Cambion
(Gain-Reset Control) 703-5314-01-04-12


INTEGRATED CIRCUITS

| CIRCUIT | DESCRIPTION | PART NO. |
| :--- | :--- | :--- |
| DESIGNATION | Bidirectional Instrumentation | MC34488A |
| U211 | Bus Transceiver | MC3448A |
| U212 | $"$ | MC3448A |
| U213 | $"$ | NE555N |
| U214 | Timer Circuit | CD4019BCN |

RESISTORS

| CIRCUIT |  |  |  |
| :---: | :---: | :---: | :---: |
| DESIGNATION | VALUE | RATING | TYPE |
| R72 | 2.05 K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt. F. |
| R73 | 100K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt. F. |
| R74 | 57.6K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt. F. |
| R75 | 19.6K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R76 | 1.96 M | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt. F. |
| R77 | 1.0K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R78 | 1.0K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R79 | 1.0K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R80 | 1.0K | 1\% $\frac{3}{4} \mathrm{~W}$ | Mt.F. |
| R81 | 2.0 M | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R82 | 3.09K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R83 | 6.65 K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R84 | 562 ohm | 1\% 年W | Mt.F. |
| R85 | 9.76 K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R86 | 2.0 M | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R87 | 511K | 1\% ${ }^{\frac{1}{4} \mathrm{~W}}$ | Mt.F. |
| R88 | 50K trimpot | (L/A Gain Adjust) | Bournes 3006P- $1-503$ |
| R89 | 50K trimpot | (L/A Offset Adjust) | Bournes $\begin{aligned} & 3006 \mathrm{P}- \\ & 1-503\end{aligned}$ |
| R200 | 4.7K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R201 | 10 ohm | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt. F. |
| R202 | 2.05 K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R203 | 19.6K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R204 | 57.6K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt. F. |
| R205 | 100K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt.F. |
| R206 | 562 ohm | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt. F. |
| R207 | 3.09 K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt. F. |
| R208 | 6.65 K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt. F. |
| R209 | 9.76 K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt. F. |
| R210 | 4.75 K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt. F. |
| R211-218 | (2) 4 Resisto | or Networks | Bournes 8018- $08-2-472$ |
| R219 | 10K | 1\% $\frac{1}{4} \mathrm{~W}$ | Mt. F. |
| R220 | 33.2K | $1 \% \frac{1}{4} \mathrm{~W}$ | Mt. F. |

This Page Intentionally Left Blank








FIGURE 6.9 DRC-84C BCD/L-A Component Layout FIGURE 6.8 DRC-84C BCD/L-A Option


FIGURE 6.11 DRC-84C IEEE Option Component Layout

